AD NO. _____
DTC PROJECT NO. 8-CO-160-UXO-021
REPORT NO. ATC-8970

STANDARDIZED

UXO TECHNOLOGY DEMONSTRATION SITE

OPEN FIELD SCORING RECORD NO. 311

SITE LOCATION:
U.S. ARMY ABERDEEN PROVING GROUND

DEMONSTRATOR:
G-TEK AUSTRALIA PTY LIMITED
3/10 HUDSON RD
ALBION QLD 4010 AUSTRALIA
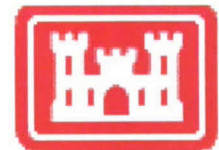
TECHNOLOGY TYPE/PLATFORM:
TM-4 MULTI SENSOR MAGNETOMETER/SLING

PREPARED BY:
U.S. ARMY ABERDEEN TEST CENTER
ABERDEEN PROVING GROUND, MD   21005-5059

APRIL 2005

DISTRIBUTION UNLIMITED, APRIL 2005.

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**14. ABSTRACT**
This scoring record documents the efforts of G-TEK to detect and discriminate inert unexploded ordnance (UXO) utilizing the APG Standardized UXO Technology Demonstration Site Open Field. The scoring record was coordinated by Larry Overbay and by the Standardized UXO Technology Demonstration Site Scoring Committee. Organizations on the committee include the U.S. Army Corps of Engineers, the Environmental, Security Technology Certification Program, the Strategic Environmental Research and Development Program, the Institute for Defense Analysis, the U.S. Army Environmental Center, and the U.S. Army Aberdeen Test Center.

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# ACKNOWLEDGMENTS

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# SECTION 1.   GENERAL INFORMATION

## 1.1   BACKGROUND

Technologies under development for the detection and discrimination of unexploded ordnance (UXO) require testing so that their performance can be characterized.  To that end, Standardized Test Sites have been developed at Aberdeen Proving Ground (APG), Maryland and U.S. Army Yuma Proving Ground (YPG), Arizona.  These test sites provide a diversity of geology, climate, terrain, and weather as well as diversity in ordnance and clutter.  Testing at these sites is independently administered and analyzed by the government for the purposes of characterizing technologies, tracking performance with system development, comparing performance of different systems, and comparing performance in different environments.

The Standardized UXO Technology Demonstration Site Program is a multi-agency program spearheaded by the U.S. Army Environmental Center (AEC).  The U.S. Army Aberdeen Test Center (ATC) and the U.S. Army Corps of Engineers Engineering Research and Development Center (ERDC) provide programmatic support.  The program is being funded and supported by the Environmental Security Technology Certification Program (ESTCP), the Strategic Environmental Research and Development Program (SERDP) and the Army Environmental Quality Technology Program (EQT).

## 1.2   SCORING OBJECTIVES

The objective in the Standardized UXO Technology Demonstration Site Program is to evaluate the detection and discrimination capabilities of a given technology under various field and soil conditions.  Inert munitions and clutter items are positioned in various orientations and depths in the ground.

The evaluation objectives are as follows:

a.  To determine detection and discrimination effectiveness under realistic scenarios that vary targets, geology, clutter, topography, and vegetation.

b.  To determine cost, time, and manpower requirements to operate the technology.

c.  To determine demonstrator's ability to analyze survey data in a timely manner and provide prioritized "Target Lists" with associated confidence levels.

d.  To provide independent site management to enable the collection of high quality, ground-truth, geo-referenced data for post-demonstration analysis.

### 1.2.1   Scoring Methodology

a.  The scoring of the demonstrator's performance is conducted in two stages.  These two stages are termed the RESPONSE STAGE and DISCRIMINATION STAGE.  For both stages, the probability of detection ($P_d$) and the false alarms are reported as receiver-operating

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characteristic (ROC) curves. False alarms are divided into those anomalies that correspond to emplaced clutter items, measuring the probability of false positive ($P_{fp}$), and those that do not correspond to any known item, termed background alarms.

b. The RESPONSE STAGE scoring evaluates the ability of the system to detect emplaced targets without regard to ability to discriminate ordnance from other anomalies. For the blind grid RESPONSE STAGE, the demonstrator provides the scoring committee with a target response from each and every grid square along with a noise level below which target responses are deemed insufficient to warrant further investigation. This list is generated with minimal processing and, since a value is provided for every grid square, will include signals both above and below the system noise level.

c. The DISCRIMINATION STAGE evaluates the demonstrator's ability to correctly identify ordnance as such and to reject clutter. For the blind grid DISCRIMINATION STAGE, the demonstrator provides the scoring committee with the output of the algorithms applied in the discrimination-stage processing for each grid square. The values in this list are prioritized based on the demonstrator's determination that a grid square is likely to contain ordnance. Thus, higher output values are indicative of higher confidence that an ordnance item is present at the specified location. For digital signal processing, priority ranking is based on algorithm output. For other discrimination approaches, priority ranking is based on human (subjective) judgment. The demonstrator also specifies the threshold in the prioritized ranking that provides optimum performance, (i.e. that is expected to retain all detected ordnance and rejects the maximum amount of clutter).

d. The demonstrator is also scored on EFFICIENCY and REJECTION RATIO, which measures the effectiveness of the discrimination stage processing. The goal of discrimination is to retain the greatest number of ordnance detections from the anomaly list, while rejecting the maximum number of anomalies arising from non-ordnance items. EFFICIENCY measures the fraction of detected ordnance retained after discrimination, while the REJECTION RATIO measures the fraction of false alarms rejected. Both measures are defined relative to performance at the demonstrator-supplied level below which all responses are considered noise, i.e., the maximum ordnance detectable by the sensor and its accompanying false positive rate or background alarm rate.

e. Based on configuration of the ground truth at the standardized sites and the defined scoring methodology, there exists the possibility of having anomalies within overlapping halos and/or multiple anomalies within halos. In these cases, the following scoring logic is implemented:

(1) In situations where multiple anomalies exist within a single $R_{halo}$, the anomaly with the strongest response or highest ranking will be assigned to that particular ground truth item.

(2) For overlapping $R_{halo}$ situations, ordnance has precedence over clutter. The anomaly with the strongest response or highest ranking that is closest to the center of a particular ground truth item gets assigned to that item. Remaining anomalies are retained until all matching is complete.

(3)   Anomalies located within any $R_{halo}$ that do not get associated with a particular ground truth item are thrown out and are not considered in the analysis.

f.   All scoring factors are generated utilizing the Standardized UXO Probability and Plot Program, version 3.1.1.

## 1.2.2   Scoring Factors

Factors to be measured and evaluated as part of this demonstration include:

a.   Response Stage ROC curves:

(1)   Probability of Detection ($P_d^{res}$).

(2)   Probability of False Positive ($P_{fp}^{res}$).

(3)   Background Alarm Rate ($BAR^{res}$) or Probability of Background Alarm ($P_{BA}^{res}$).

b.   Discrimination Stage ROC curves:

(1)   Probability of Detection ($P_d^{disc}$).

(2)   Probability of False Positive ($P_{fp}^{disc}$).

(3)   Background Alarm Rate ($BAR^{disc}$) or Probability of Background Alarm ($P_{BA}^{disc}$).

c.   Metrics:

(1)   Efficiency (E).

(2)   False Positive Rejection Rate ($R_{fp}$).

(3)   Background Alarm Rejection Rate ($R_{BA}$).

d.   Other:

(1)   Probability of Detection by Size and Depth.

(2)   Classification by type (i.e., 20-, 40-, 105-mm, etc.).

(3)   Location accuracy.

(4)   Equipment setup, calibration time and corresponding man-hour requirements.

(5)   Survey time and corresponding man-hour requirements.

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(6) Reacquisition/resurvey time and man-hour requirements (if any).

(7) Downtime due to system malfunctions and maintenance requirements.

## 1.3  STANDARD AND NONSTANDARD INERT ORDNANCE TARGETS

The standard and nonstandard ordnance items emplaced in the test areas are listed in Table 1. Standardized targets are members of a set of specific ordnance items that have identical properties to all other items in the set (caliber, configuration, size, weight, aspect ratio, material, filler, magnetic remanence, and nomenclature). Nonstandard targets are inert ordnance items having properties that differ from those in the set of standardized targets.

**TABLE 1.  INERT ORDNANCE TARGETS**

| Standard Type | Nonstandard (NS) |
|---|---|
| 20-mm Projectile M55 | 20-mm Projectile M55 |
|  | 20-mm Projectile M97 |
| 40-mm Grenades M385 | 40-mm Grenades M385 |
| 40-mm Projectile MKII Bodies | 40-mm Projectile M813 |
| BDU-28 Submunition |  |
| BLU-26 Submunition |  |
| M42 Submunition |  |
| 57-mm Projectile APC M86 |  |
| 60-mm Mortar M49A3 | 60-mm Mortar (JPG) |
|  | 60-mm Mortar M49 |
| 2.75-inch Rocket M230 | 2.75-inch Rocket M230 |
|  | 2.75-inch Rocket XM229 |
| MK 118 ROCKEYE |  |
| 81-mm Mortar M374 | 81-mm Mortar (JPG) |
|  | 81-mm Mortar M374 |
| 105-mm HEAT Rounds M456 |  |
| 105-mm Projectile M60 | 105-mm Projectile M60 |
| 155-mm Projectile M483A1 | 155-mm Projectile M483A |
|  | 500-lb Bomb |

JPG = Jefferson Proving Ground
HEAT = high-explosive antitank

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## SECTION 2.   DEMONSTRATION

## 2.1   DEMONSTRATOR INFORMATION

### 2.1.1   Demonstrator Point of Contact (POC) and Address

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### 2.1.2   System Description (provided by demonstrator)

**Sensor System Description.**

The hand-held TM-4 magnetometer system consisting of the following components:

| Item | Manufacturer | Model |
|---|---|---|
| Magnetometer Control Module | G-TEK | TM-4 |
| Cs Vapor type TMI Sensors | Geometrics | G822AS |
| Base-station magnetometer | G-TEK | TM-4 |
| Digital Global Positioning System (DGPS) | NovAtel | Rt-2/OEM-4 |
| Odometer | G-TEK | TM-4D |

The TM-4 is a self-contained magnetometer system, which may be configured with up to four, optically pumped magnetic sensors each recording the total magnetic field intensity in units of nT to a resolution of 0.01 nT.   These sensors will be mounted in an array oriented perpendicular to the survey direction permitting up to four sensor transects to be recorded simultaneously in the open terrain with high survey productivity.   The proposed sensor separation is 300 mm and ground clearance 250 mm.   The measurement rate from each sensor is selectable from nominally 50 per second at 0.003 nT resolution to 400 per second at 0.08 nT. The high measurement rate permits effective real-time filtering of 50/60 Hz electromagnetic interference prior to recording position or time-based measurements at intervals appropriate to the application (in this case 50 mm or 10 Hz).   The TM-4 interfaces with both industry standard real-time kinematic (RTK) DGPS and proprietary cotton thread based odometer systems.   This provides versatile time or position-based positioning that is adaptable to varied terrain and vegetation conditions.   A key attribute of the TM-4 is the operating system software that provides a continuous set of data quality monitors reducing the need to resurvey and improving data quality.   In particular there are audio and graphic displays and alarms monitoring sensor signal quality, position data quality and navigation aids.

A two-person crew operates the TM-4 system. One-person carries the sensor array to which is attached the DGPS antenna and odometer system. The array measures 1500 mm length by the array width, which in this case will be 900 mm. The quad-sensor array weighs 10 kg. The second person operates the navigation and data acquisition hardware carried in a backpack with batteries. The backpack measures 600 by 400 by 250 mm and weighs approximately 12 kg. The user interface is a hand-held personal computer (PC). A 5-meter cable eliminating interference at the sensors from the other hardware separates the two operators. There are no specific safety hazards identified with the use of this equipment.

Data processing consists of magnetic base-station subtraction, optional band-pass spatial filtering to enhance particular source depths, grading and imaging. Interpretation of picked anomalies involves classification (by type) and ranking (by probability UXO) using model inversion involving both magnetic remanence and the use of a database of anticipated UXO types. Products are data images and dig sheets conforming to DID OE-005-05.02 standards.

The TM-4 has been used with our odometer system by industry and the Australian Department of Defense operators for over 14 years and with DGPS for over 7 years. The odometer remains the positioning technology of choice in adverse terrains (such as wooded scenarios), DGPS is preferred in open environments. Combined, they meet the requirements of most situations.

**Positioning System Description.**

G-TEK propose using a combination of the following survey/navigation technologies:

| Item | Manufacturer | Model |
|---|---|---|
| DGPS | NovAtel | RT-2/OEM-4 |
| Odometer | G-TEK | TM-4D |
| Polychain | PEKO | 100M |
| Siters | Various | Generic traffic cones. Wooden Dowels and flagging |

The TM-4 magnetometer system interfaces with both industry standard RTK DGPS and proprietary cotton thread based odometer systems providing versatile time or position-based positioning that is adaptable to varied terrain and vegetation conditions. In both cases, where an UXO detection standard of survey coverage is required, G-TEK operators use a pre-established control grid and visual sighters for straight-line navigation, and use the DGPS or odometer primarily for data positioning.

**Using DGPS in the Open Area.**

DGPS is the technology of choice in situations where satellite coverage is reliable. In this case, any of the industry standard RTK systems may be used although in this program we propose using the NovAtel RT-2 system (Ashtech Z-Extreme as a backup). Our preference is to establish a Global Positioning System (GPS) base-station on a monument that is within 1 km of the survey area and to use a radio link to the roving GPS receiver. In the roving instrumentation,

sensor data is time tagged with GPS time and transformed DGPS positions (and the raw National Maritime Electronics Association (NMEA) GPS data for backup) are recorded. In this way, sensor data is positioned in post processing to achieve position accuracy better than 5 cm. Prior to commencing survey, the roving GPS is located at a known reference to confirm the integrity of the system and transformations used.

### Using the Odometer in the Wooded Area.

The control grid setup will combine the use of DGPS and traditional survey techniques. Navigation will be done the same as described above. However, 5 meters before the commencement of each new transect, the cotton thread is tied to either vegetation or a small peg anchored to the ground. When each control line is reached, a distance mark is recorded in the TM-4 prior to moving the cone. At the completion of each survey grid section the cotton is gathered and removed from the site. In post-processing, linear error distribution delivers positional accuracy that is typically less than 0.1 percent of the distance between control lines (0.1 percent of 25 m delivers 25 mm accuracy in this case.) Because the odometer is used in more adverse terrain including forests, protocols have been developed using the electronic notepad facility of the TM-4 for recording the location of obstacles (e.g., trees) and the direction taken around these. Thus if a UXO is detected close to such a tree, the validation team will know which side of the tree to search. Experience over many years surveying in forested conditions has indicated that an RMS target position error of less than 300 mm can be anticipated with the greatest errors occurring where obstacles are circumvented. These errors are not cumulative and are comparable with the interpreted target position errors achieved using DGPS.



Figure 1. TM-4 magnetic data acquisition system.

### 2.1.3 Data Processing Description (provided by demonstrator)

**Data Processing:**

The data will be processed in the following sequence (the software used at each step is noted in square brackets):

**Data Acquisition:**

a. The output from up to four sensors of magnetometer data will be recorded at 10 Hz in GPS mode and 5 cm in cotton odometer distance-mode G-TEK's TM-4 magnetometer acquisition software.

b. The magnetometer data will be precisely time-tagged with reference to the connected GPS, at 1 Hz.

c. The GPS positions and GPS quality information will be logged at no less than 1 Hz in the required coordinate system. Extraneous position data will be either automatically or manually flagged as "not required". Raw untransformed GPS NMEA standard strings will also be logged as backup [G-TEK's SurvNav].

d. In cotton odometer mode the precise vertices of the survey boundary and control lines are measured with the RTK-DGPS and entered into the magnetometer. The operator will be responsible for hitting the start and stop button for each line [G-TEK's TM-4 magnetometer acquisition software].

e. A magnetometer base-station will record time tagged, stationary, temporal variations at 10 Hz.

f. All data will be transferred from the field devices to the processing computer and a "Field Data Sheet" completed by each crew leader ("Attachment A, DID OE-005-05.01").

g. The GPS data will automatically be assigned unique line-numbers during the data acquisition. The data will be indexed by these line-numbers during the line-based post-processing (i.e., up to the grading stage). Extraneous data will be automatically and manually flagged as "not required" [G-TEK's SurvNav].

**Post-Processing by the Processing Geophysicist:**

a. The GPS track will be checked, edited and smoothed as required [GEOSOFT]. For cotton positioning the distance recorded by the precise electronic odometer will be compared to the expected known length of each line. Variations exceeding a certain tolerance will trigger the issue of a "Line-ReDo" order to the field crew leader [G-TEK's Distance-Based Processing Software].

b.  At this stage the positions of individual sensors will be calculated from the precisely measured sensor-GPS antennae offsets and the instantaneous track direction of the array.  These individual sensor track positions will be referenced as sub-lines 1 to 4.  In distance-mode this stage is automated [G-TEK's Preprocessing software].

c.  The GPS, rover magnetometer and base magnetometer data will be merged on the 10-z time-base during post-processing and corrections will be then applied [GEOSOFT].  In distance-mode just the magnetometer and base-station data are merged, positioned and corrected.

d.  The magnetometer data will be automatically and manually scanned for the removal of invalid data [GEOSOFT].

e.  At this stage the raw data will be exported to GEOSOFT ASCII XYZ format (with line reference headers and column labels) complying with the Raw Data Submittal guidelines on the "Standardized UXO Technology Demonstration Site - Submission for Scoring" web site.  The data will then be written to compact disk (CD) for submission [GEOSOFT].

f.  The data will then be re-sampled to a distance-base of no greater than 0.05 meter to facilitate band-pass filtering to reduce effects from wavelengths determined to be inconsistent with the target anomalies (e.g., deep geology, system noise) [G-TEK's GEOSOFT GXs].

g.  The data will then be graded to a square mesh no greater than 0.05 meter, using minimum curvature grading and using the GEOSOFT "FLOAT" grid format [GEOSOFT].

h.  The graded data will then be loaded into the viewing and interpretation software for semi-automated interpretation.  This process involves the automatic selection of associated maximums and minimums whose amplitudes exceed the interpretation threshold.  These are then manually checked.  The selected anomalies are then inverted against a list of target items to find the best fit and the degree of magnetic remanence required.  Use will be made of the ground-truth data from the Calibration Lane to fine-tune the discrimination parameters.  This will then provide the basis for the discrimination classification and prioritization in the submittal [G-TEK's MagSys software].

i.  The information from the selected anomalies ("Processed Data") will then be imported into a Microsoft (MS)-Excel spreadsheet for formatting for presentation as a dig sheet based on the template "Attachment C, DID OE-005-05.01" and written to CD for submittal [G-TEK's EOD Reporter MS Excel macro].

j.  The dig sheet data ("Processed Data") will also be reformatted to comply with the Processed Data Submittal guidelines on the "Standardized UXO Technology Demonstration Site - Submission for Scoring" web site.  The data will then be written to CD for submission [MS EXCEL].

k.  The color contour, processed magnetic grid-image, with selected anomalies marked will be presented based on the map template "Attachment D, DID OE-005-05.01" also on CD [GEOSOFT].

**Discrimination.**

The discrimination will be performed using G-TEK's MagSys display, interpretation and discrimination software. This tool enables the selected anomalies to be inverted to a series of spheroids representing UXO and cluster items know to exist at this site. A user selectable amount of remanence will be permitted into inversion parameters. The dipole moment direction, and strength will also be listed for each item. These discrimination parameters will then be fine-tuned using the Calibration Lane data.

### 2.1.4  Data Submission Format

Data were submitted for scoring in accordance with data submission protocols outlined in the Standardized UXO Technology Demonstration Site Handbook. These submitted data are not included in this report in order to protect ground truth information.

### 2.1.5  Demonstrator Quality Assurance (QA) and Quality Control (QC) (provided by demonstrator)

Quality Control. G-TEK will perform QC steps and tests using the DID OE_005.05.02 using the following QC frequency:

| Test Description | Power on | Day start | Day start/end | First day | Repeat last 2 grid lines |
|---|---|---|---|---|---|
| Equipment warm-up | 5-min. | | | | |
| Record sensor offsets | | X | | | |
| Personnel test | | X | | | |
| Vibration test | | X | | | |
| Static and spike test | | | 3 min/1 min/3 min | | |
| Six line test | | | | X | |
| Repeat line test | | | | | X |
| Visit survey point | | | X | | |

Equipment/Electronics warm-up for 5 minutes: This allows for thermal stabilization of electronics.

Record Relative Sensor Position (1 cm accuracy): Document relative navigation and sensor offsets, detector separation, and detector heights above the ground surface.

Personnel Test (10 emu at 10 cm from the sensors): To ensure survey personnel have removed all potential metallic interference sources from their bodies.

Shake Test (<10 emu at 10 cm from the sensor): To identify and replace shorting cables and broken pin-outs on connectors, with the instrument held in a static position and collecting data, cables are shaken to test fro shorts and broken pin-outs. Repaired or replaced cables are rigorously retested before use.

Static Background and Static Standard Response (Spike) Test (10 emu): To quantify instrument background readings, electronic drift, locate potential interference spikes, and determine impulse response and repeatability of the instrument to a standard test item. Review in real-time.

Six Line Test (Repeatability of Response Amplitude +/-20 percent, Positional Accuracy +/-20 cm): To document latency, heading effects, repeatability of response amplitude, and positional accuracy. The test line will be well marked to facilitate data collection over the exact same line each time the test is performed. Background response over the test line is established in Lines 1 and 2. A standard test item, such as a steel trailer hitch ball will be used for Lines 3 through 6.

Visit Survey Point (±25 mm): Check that GPS base location and transformations are correct.

Repeat Last Two Lines of Each Grid (Repeatability of Response Amplitude +/-20 percent, Positional Accuracy +/-20 cm): To determine positional and geophysical data repeatability.

TM-4 MAG Calibration (>250 emu): By the use of calibration device known as an "EMUlator" (developed by G-TEK for the purpose of establishing the integrity of the TM-4 MAG) the EMUlator is placed touching the rim of the sensor coil and data is recorded for a period of 60 seconds. The EMUlator delivers a controlled response to the excitation transmitted by the TM-4 MAG.

Sensor Elevation: The TM-4 MAG will be operated at a low but uniform elevation. To help the operator achieve the elevation, a piece of non-conductive tape will be attached to the back of the coil such that it hangs 10 cm. The operator then maintains the end of the tape just touching the ground (or where he judges the ground to be below the grass cover). Higher elevations due to vegetation will be noted.

Data Processing: The data processing and interpretations will be checked by a second geophysicist, and all intermediate processing stages of the data will be retained in meaningfully named columns within GEOSOFT for this purpose. All data will be backed up daily.

Quality Assurance (QA). The data collected during the pre-survey QC checks will be processed, documented and checked by the Data Processing Geophysicist to assure that the entire system will provide the quality to achieve the desired outcome of detecting and correctly discriminating the UXO items down to their specified depths as determined by the site conditions.

- The RT-DGPS systems have a quoted accuracy of 2.0 cm + 0.1 mm/(km to the base-station) Central Error Probability (CEP) in dynamic mode. In practice, however, assuming a consistent differential correction of 1 per second and a baseline less than 2 km the worst-case absolute accuracy will be ±5.0 cm with a typical accuracy of ±2.5 cm. Synchronization errors between the EM detector and the GPS will be reduced by calibration down to the resolution of the sampling rate of 0.03 second. In sloping terrain there will be an additional error when the GPS antennae pole varies from the vertical.

- In the forested areas the use of an electronic cotton odometer system to track the sensors' positions along the line will be used. This system has an inherent along-line accuracy of <1 percent and a resolution of 5 cm. However, when the start and the end positions are known, this error is reduced to <0.2 percent of the distance between known points. In this case we propose to have control lines at no greater than 25 m intervals. That is an accuracy of $\pm 5$ cm.

Estimated Accuracy of the Navigation System: The primary navigation method will be the use of accurately placed sighters along the control lines. The operators must then keep at least two sighters in line with the center point of the sensor array. This navigation technique will be used with both the cotton and the GPS positions tracking systems. The advantage of this system is its simplicity and applicability to difficult situations. The accuracy of this system depends on the accuracy of the pegged grid and the diligence of the operators. The anticipated typical across-line error is $\pm 10$ cm. The effective swath width of the 2-sensor array will be 1.2 meter. The nominal lane space of 1.0 meter will allow for cross-line navigation variations.

QA of Positioning: The GEOSOFFT DoD UXO QA system will be used to report on "Line Coverage Comparisons." This report will allow the quantifications of the data positioning on a line basis. Lines that fail will trigger "Re-Do" orders to the field crew leaders.

QA of Sensor Data Quality: The quality of each sub-line of data will be quantified as the largest distance with consecutive invalid sensor data. If a sub-line fails the criteria then a "Re-Do" order will be triggered. The magnetometer base-station will be subjected to similar quality quantification and recording processes.

QA Based on a Two Traverse Resurvey: The sensor data and interpretation will be compared to the original and whole-system repeatability will be reported for quality assurance.

QA of Data Processing: During data processing the dates and times of the various data streams will be automatically correlated by the software. A second QC geophysicist will check the quality of the raw data, the selected processing parameters, interpretation parameters, and the final grid data. The data will then provide QA of the interpretation by checking each grid of the data for missed anomalies. Thee QC geophysicist can then add but not delete more anomalies. The QC geophysicist will then repeat the discrimination process on 10 percent of the anomalies and compare the results. The process will assure the quality of the final prioritized dig sheet results. The results will allow the generation of quantified assured depth of detection verse caliber graph.

### 2.1.6 **Additional Records**

The following record(s) by this vendor can be accessed via the Internet as MicroSoft Word documents at www.uxotestsites.org. The Blind Grid counterpart to this report is Scoring Record #268.

## 2.2 APG SITE INFORMATION

### 2.2.1 <u>Location</u>

The APG Standardized Test Site is located within a secured range area of the Aberdeen Area. The Aberdeen Area of APG is located approximately 30 miles northeast of Baltimore at the northern end of the Chesapeake Bay. The Standardized Test Site encompasses 17 acres of upland and lowland flats, woods and wetlands.

### 2.2.2 <u>Soil Type</u>

According to the soils survey conducted for the entire area of APG in 1998, the test site consists primarily of Elkton Series type soil (ref 2). The Elkton Series consist of very deep, slowly permeable, poorly drained soils. These soils formed in silty aeolin sediments and the underlying loamy alluvial and marine sediments. They are on upland and lowland flats and in depressions of the Mid-Atlantic Coastal Plain. Slopes range from 0 to 2 percent.

ERDC conducted a site-specific analysis in May of 2002 (ref 3). The results basically matched the soil survey mentioned above. Seventy percent of the samples taken were classified as silty loam. The majority (77 percent) of the soil samples had a measured water content between 15- and 30-percent with the water content decreasing slightly with depth.

For more details concerning the soil properties at the APG test site, go to www.uxotestsites.org on the web to view the entire soils description report.

### 2.2.3 <u>Test Areas</u>

A description of the test site areas at APG is included in Table 2.

**TABLE 2.   TEST SITE AREAS**

| Area | Description |
|------|-------------|
| Calibration Grid | Contains 14 standard ordnance items buried in six positions at various angles and depths to allow demonstrator to calibrate their equipment. |
| Blind Test Grid | Contains 400 grid cells in a 0.2-hectare (0.5 acre) site. The center of each grid cell contains ordnance, clutter or nothing. |
| Open Field | A 4-hectare (10-acre) site containing open areas, dips, ruts and obstructions that challenge platform systems or hand held detectors. The challenges include a gravel road, wet areas and trees. The vegetation height varies from 15 to 25 cm. |

# SECTION 3.   FIELD DATA

## 3.1   DATE OF FIELD ACTIVITIES (15 through 21 October 2003)

## 3.2   AREAS TESTED/NUMBER OF HOURS

Areas tested and total number of hours operated at each site are summarized in Table 3.

### TABLE 3.   AREAS TESTED AND NUMBER OF HOURS

| Area | Number of Hours |
|---|---|
| Calibration Lanes | 0.91 |
| Open Field | 57.25 |

## 3.3   TEST CONDITIONS

### 3.3.1   Weather Conditions

An APG weather station located approximately one mile west of the test site was used to record average temperature and precipitation on a half hour basis for each day of operation. The temperatures listed in Table 4 represent the average temperature during field operations from 0700 to 1700 hours while precipitation data represents a daily total amount of rainfall. Hourly weather logs used to generate this summary are provided in Appendix B.

### TABLE 4.   TEMPERATURE/PRECIPITATION DATA SUMMARY

| Date, 2003 | Average Temperature, °F | Total Daily Precipitation, in. |
|---|---|---|
| October 15 | 61.12 | 0.11 |
| October 16 | 61.73 | 0.00 |
| October 17 | 55.15 | 0.05 |
| October 18 | 54.36 | 0.00 |
| October 20 | 55.24 | 0.00 |
| October 21 | 67.51 | 0.00 |

### 3.3.2   Field Conditions

G-TEK surveyed the Open Field area with the TM-4 MAG on 15 through 21 October 2003. The Open field area was muddy due to rain events which occurred before and during testing.

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### 3.3.3 Soil Moisture

Three soil probes were placed at various locations within the site to capture soil moisture data: Calibration, Mogul, and Wooded areas. Measurements were collected in percent moisture and were taken twice daily (morning and afternoon) from five different soil depths (1 to 6 in., 6 to 12 in., 12 to 24 in., 24 to 36 in., and 36 to 48 in.) from each probe. Soil moisture logs are included in Appendix C.

### 3.4 FIELD ACTIVITIES

#### 3.4.1 Setup/Mobilization

These activities included initial mobilization and daily equipment preparation and break down. A three-person crew took 5 hours and 10 minutes to perform the initial setup and mobilization. There was 6 hours and 10 minutes of daily equipment preparation and end of the day equipment break down lasted 3 hours and 35 minutes.

#### 3.4.2 Calibration

G-TEK spent a total of 55 minutes in the calibration lanes, 50 minutes of which was spent collecting data. An additional 3 hours and 5 minutes were spent calibrating while surveying the Open Field.

#### 3.4.3 Downtime Occasions

Occasions of downtime are grouped into five categories: equipment/data checks or equipment maintenance, equipment failure and repair, weather, Demonstration Site issues, or breaks/lunch. All downtime is included for the purposes of calculating labor costs (section 5) except for downtime due to Demonstration Site issues. Demonstration Site issues, while noted in the Daily Log, are considered non-chargeable downtime for the purposes of calculating labor costs and are not discussed. Breaks and lunches are discussed in this section and billed to the total Site Survey area.

**3.4.3.1 Equipment/data checks, maintenance.** Equipment data checks and maintenance activities accounted for 4 hours and 50 minutes of site usage time. These activities included changing out batteries and routine data checks to ensure the data was being properly recorded/collected. G-TEK spent an additional 55 minutes for breaks and lunches.

**3.4.3.2 Equipment failure or repair.** Two minor equipment failures occurred while surveying in the Open Field Area. On 17 October, a cable became loose during survey. Several minutes passed before realizing the problem, the cable was then reconnected and no further problem occurred. On 18 October, a 10 minute failure occurred due to poor GPS satellite quality. The problem rectified itself and no other problems occurred.

**3.4.3.3 Weather.** No weather delays occurred during the survey.

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### 3.4.4 Data Collection

G-TEK spent a total time of 57 hours and 15 minutes in the Open Field area, 31 hours and 45 minutes of which was spent collecting data.

### 3.4.5 Demobilization

The G-TEK survey crew went on to conducted a full demonstration of the site. Therefore, demobilization did not occur until 24 October 2003. On that day, it took the crew 1-hour and 35 minutes to break down and pack up their equipment.

### 3.5 PROCESSING TIME

G-TEK submitted the raw data from the demonstration activities on the last day of the demonstration, as required. The scoring submittal data was also provided within the required 30-day timeframe.

### 3.6 DEMONSTRATOR'S FIELD PERSONNEL

Mr. Peter Clark, Site Manager
Mr. Paul O'Donnell, Geophysicist
Mr. Bruce Symans, Crew Leader
Mr. Graham Browne, Field Technician
Mr. Terry Foot, Data Acquisition, Grid Setup

### 3.7 DEMONSTRATOR'S FIELD SURVEYING METHOD

G-TEK started surveying the Open field area in the southwest portion and surveyed in a south/north direction. One lane was surveyed and then the demonstrator returned to the beginning of the next lane, until completion. Lanes were layed out in 50-meter intervals, where appropriate.

### 3.8 SUMMARY OF DAILY LOGS

Daily logs capture all field activities during this demonstration and are located in Appendix D. Activities pertinent to this specific demonstration are indicated in highlighted text.

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## SECTION 4.   TECHNICAL PERFORMANCE RESULTS

### 4.1  ROC CURVES USING ALL ORDNANCE CATEGORIES

Figure 2 shows the probability of detection for the response stage ($P_d^{res}$) and the discrimination stage ($P_d^{disc}$) versus their respective probability of false positive.  Figure 3 shows both probabilities plotted against their respective background alarm rate.  Both figures use horizontal lines to illustrate the performance of the demonstrator at two demonstrator-specified points:  at the system noise level for the response stage, representing the point below which targets are not considered detectable, and at the demonstrator's recommended threshold level for the discrimination stage, defining the subset of targets the demonstrator would recommend digging based on discrimination.  Note that all points have been rounded to protect the ground truth.

The overall ground truth is composed of ferrous and non-ferrous anomalies.  Due to limitations of the magnetometer, the non-ferrous items cannot be detected.  Therefore, the ROC curves presented in this section are based on the subset of the ground truth that is solely made up of ferrous anomalies.
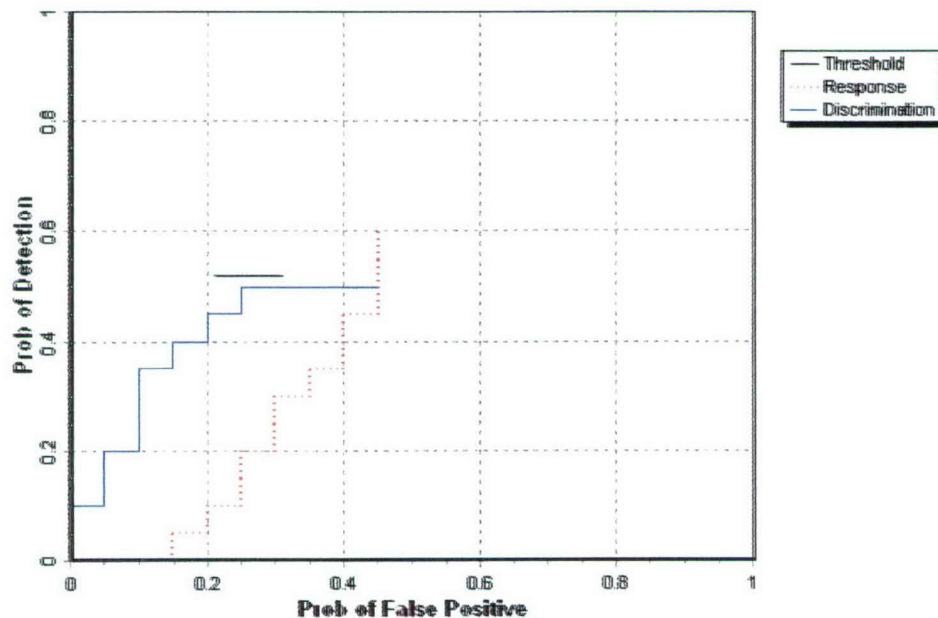


Figure 2.  TM-4 MAG open field probability of detection for response and discrimination stages versus their respective probability of false positive over all ordnance categories combined.
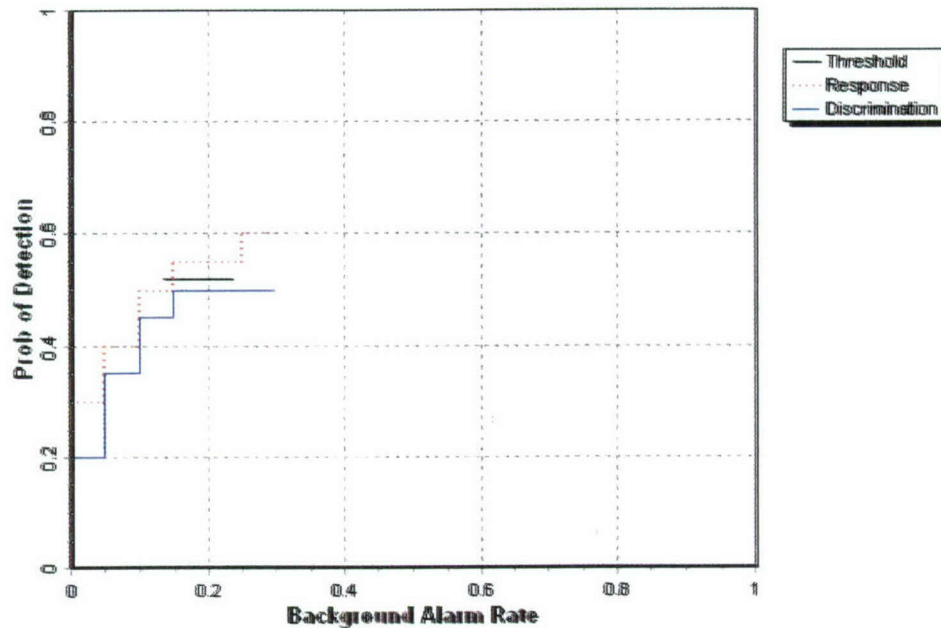
Figure 3. TM-4 MAG open field probability of detection for response and discrimination stages versus their respective background alarm rate over all ordnance categories combined.

## 4.2 ROC CURVES USING ORDNANCE LARGER THAN 20 MM

Figure 4 shows the probability of detection for the response stage ($P_d^{res}$) and the discrimination stage ($P_d^{disc}$) versus their respective probability of false positive when only targets larger than 20 mm are scored. Figure 5 shows both probabilities plotted against their respective probability of background alarm rate. Both figures use horizontal lines to illustrate the performance of the demonstrator at two demonstrator-specified points: at the system noise level for the response stage, representing the point below which targets are not considered detectable, and at the demonstrator's recommended threshold level for the discrimination stage, defining the subset of targets the demonstrator would recommend digging based on discrimination. Note that all points have been rounded to protect the ground truth.

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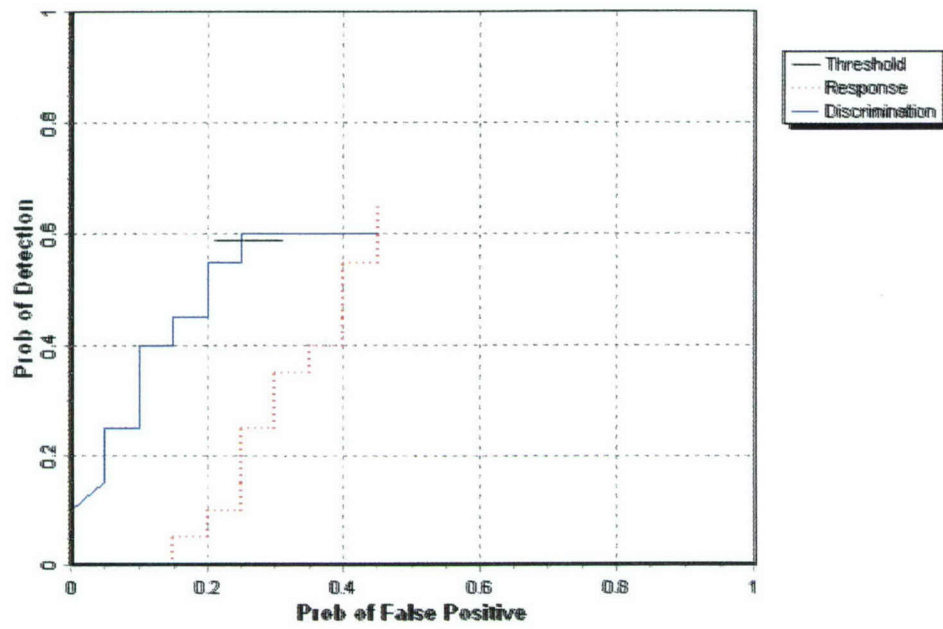
Figure 4.  TM-4 MAG open field probability of detection for response and discrimination stages versus their respective probability of false positive for all ordnance larger than 20 mm.
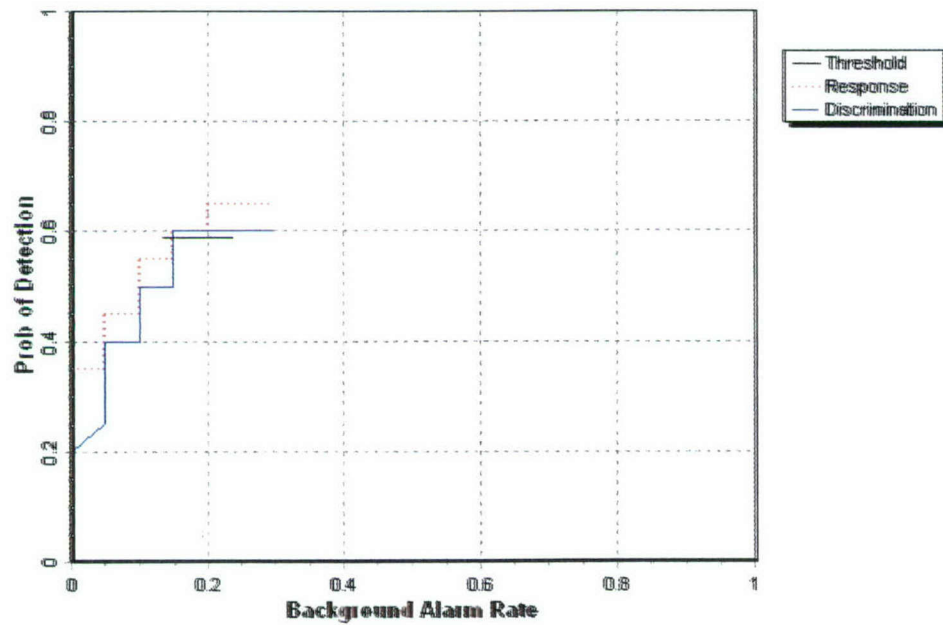


Figure 5.  TM-4 MAG open field probability of detection for response and discrimination stages versus their respective background alarm rate for all ordnance larger than 20 mm.

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## 4.3 PERFORMANCE SUMMARIES

Results for the Open Field test, broken out by size, depth and nonstandard ordnance, are presented in Tables 5a and 5b (for cost results, see section 5). Results by size and depth include both standard and nonstandard ordnance. The results by size show how well the demonstrator did at detecting/discriminating ordnance of a certain caliber range (see app A for size definitions). The results are relative to the number of ordnances emplaced. Depth is measured from the geometeric center of anomolies.

The RESPONSE STAGE results are derived from the list of anomalies above the demonstrator-provided noise level. The results for the DISCRIMINATION STAGE are derived from the demonstrator's recommended threshold for optimizing UXO field cleanup by minimizing false digs and maximizing ordnance recovery. The lower 90-percent confidence limit on probability of detection and probability of false positive was calculated assuming that the number of detections and false positives are binomially distributed random variables. All results in Tables 5a and 5b have been rounded to protect the ground truth. However, lower confidence limits were calculated using actual results.

The overall ground truth is composed of ferrous and non-ferrous anomalies. Due to limitations of the magnetometer, the non-ferrous items cannot be detected. Therefore, the summary presented in Table 5a exhibits results based on the subset of the ground truth that is solely the ferrous anomalies. Table 5b exhibits results based on the full ground truth. All other tables presented in this section are based on scoring against the ferrous only ground truth. The response stage noise level and recommended discrimination stage threshold values are provided by the demonstrator.

### TABLE 5a. SUMMARY OF OPEN FIELD RESULTS (FERROUS ONLY)

| Metric | Overall | Standard | Nonstandard | By Size | | | By Depth, m | | |
|---|---|---|---|---|---|---|---|---|---|
| | | | | Small | Medium | Large | < 0.3 | 0.3 to <1 | >= 1 |
| RESPONSE STAGE | | | | | | | | | |
| $P_d$ | 0.60 | 0.65 | 0.55 | 0.45 | 0.60 | 0.85 | 0.60 | 0.60 | 0.55 |
| $P_d$ Low 90% Conf | 0.57 | 0.60 | 0.47 | 0.38 | 0.54 | 0.77 | 0.56 | 0.55 | 0.47 |
| $P_d$ Upper 90% Conf | 0.64 | 0.70 | 0.60 | 0.51 | 0.66 | 0.89 | 0.67 | 0.68 | 0.64 |
| $P_{fp}$ | 0.45 | - | - | - | - | - | 0.45 | 0.50 | 055 |
| $P_{fp}$ Low 90% Conf | 0.45 | - | - | - | - | - | 0.41 | 0.47 | 0.38 |
| $P_{fp}$ Upper 90% Conf | 0.49 | - | - | - | - | - | 0.47 | 0.53 | 0.74 |
| BAR | 0.30 | - | - | - | - | - | - | - | - |
| DISCRIMINATION STAGE | | | | | | | | | |
| $P_d$ | 0.50 | 0.55 | 0.45 | 0.30 | 0.55 | 0.80 | 0.50 | 0.55 | 0.50 |
| $P_d$ Low 90% Conf | 0.48 | 0.51 | 0.40 | 0.26 | 0.47 | 0.71 | 0.43 | 0.50 | 0.42 |
| $P_d$ Upper 90% Conf | 0.56 | 0.61 | 0.53 | 0.39 | 0.59 | 0.84 | 0.54 | 0.63 | 0.60 |
| $P_{fp}$ | 0.25 | - | - | - | - | - | 0.25 | 0.25 | 0.40 |
| $P_{fp}$ Low 90% Conf | 0.24 | - | - | - | - | - | 0.23 | 0.23 | 0.21 |
| $P_{fp}$ Upper 90% Conf | 0.28 | - | - | - | - | - | 0.29 | 0.28 | 0.57 |
| BAR | 0.20 | - | - | - | - | - | - | - | - |

Response Stage Noise Level: 0.02
Recommended Discrimination Stage Threshold: 0.50

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# TABLE 5b. SUMMARY OF OPEN FIELD RESULTS (FULL GROUND TRUTH)

| Metric | Overall | Standard | Nonstandard | By Size | | | By Depth, m | | |
|---|---|---|---|---|---|---|---|---|---|
| | | | | Small | Medium | Large | < 0.3 | 0.3 to <1 | >= 1 |
| RESPONSE STAGE | | | | | | | | | |
| $P_d$ | 0.55 | 0.55 | 0.50 | 0.30 | 0.60 | 0.85 | 0.50 | 0.55 | 0.55 |
| $P_d$ Low 90% Conf | 0.49 | 0.52 | 0.42 | 0.27 | 0.54 | 0.77 | 0.45 | 0.50 | 0.45 |
| $P_d$ Upper 90% Conf | 0.57 | 0.61 | 0.54 | 0.38 | 0.66 | 0.89 | 0.56 | 0.62 | 0.63 |
| $P_{fp}$ | 0.45 | - | - | - | - | - | 0.45 | 0.50 | 0.55 |
| $P_{fp}$ Low 90% Conf | 0.44 | - | - | - | - | - | 0.39 | 0.46 | 0.38 |
| $P_{fp}$ Upper 90% Conf | 0.48 | - | - | - | - | - | 0.46 | 0.52 | 0.74 |
| BAR | 0.30 | - | - | - | - | - | - | - | - |
| | | | | | | | | | |
| $P_d$ | 0.45 | 0.50 | 0.40 | 0.25 | 0.55 | 0.80 | 0.40 | 0.50 | 0.50 |
| $P_d$ Low 90% Conf | 0.42 | 0.44 | 0.36 | 0.19 | 0.47 | 0.71 | 0.35 | 0.45 | 0.40 |
| $P_d$ Upper 90% Conf | 0.49 | 0.53 | 0.47 | 0.29 | 0.59 | 0.84 | 0.45 | 0.57 | 0.58 |
| $P_{fp}$ | 0.25 | - | - | - | - | - | 0.25 | 0.25 | 0.40 |
| $P_{fp}$ Low 90% Conf | 0.24 | - | - | - | - | - | 0.23 | 0.22 | 0.21 |
| $P_{fp}$ Upper 90% Conf | 0.27 | - | - | - | - | - | 0.28 | 0.28 | 0.57 |
| BAR | 0.20 | - | - | - | - | - | - | - | - |

Response Stage Noise Level: 0.02
Recommended Discrimination Stage Threshold 0.50

## 4.4 EFFICIENCY, REJECTION RATES, AND TYPE CLASSIFICATION

Efficiency and rejection rates are calculated to quantify the discrimination ability at specific points of interest on the ROC curve: (1) at the point where no decrease in $P_d$ is suffered (i.e., the efficiency is by definition equal to one) and (2) at the operator selected threshold. These values are reported in Table 6.

### TABLE 6. EFFICIENCY AND REJECTION RATES

| | Efficiency (E) | False Positive Rejection Rate | Background Alarm Rejection Rate |
|---|---|---|---|
| At Operating Point | 0.86 | 0.45 | 0.42 |
| With No Loss of $P_d$ | 1.00 | 0.09 | 0.03 |

At the demonstrator's recommended setting, the ordnance items that were detected and correctly discriminated were further scored on whether their correct type could be identified (table 8). Correct type examples include "20-mm projectile, 105-mm HEAT Projectile, and 2.75-inch Rocket". A list of the standard type declaration required for each ordnance item was provided to demonstrators prior to testing. For example, the standard type for the three example items are 20mmP, 105H, and 2.75in, respectively.

**TABLE 7. CORRECT TYPE CLASSIFICATION
OF TARGETS CORRECTLY
DISCRIMINATED AS UXO**

| Size | Percentage Correct |
|------|--------------------|
| Small | 17.6 |
| Medium | 20.0 |
| Large | 43.9 |
| Overall | 28.2 |

## 4.5 LOCATION ACCURACY

The mean location error and standard deviations appear in Table 8. These calculations are based on average missed depth for ordnance correctly identified in the discrimination stage. Depths are measured from the closest point of the ordnance to the surface. For the Blind Grid, only depth errors are calculated, since (X, Y) positions are known to be the centers of each grid square.

**TABLE 8. MEAN LOCATION ERROR AND
STANDARD DEVIATION (M)**

| | Mean | Standard Deviation |
|------|------|--------------------|
| Northing | 0.12 | 0.18 |
| Easting | -0.06 | 0.17 |
| Depth | 0.18 | 0.22 |

# SECTION 5.   ON-SITE LABOR COSTS

A standardized estimate for labor costs associated with this effort was calculated as follows: the first person at the test site was designated "supervisor", the second person was designated "data analyst", and the third and following personnel were considered "field support". Standardized hourly labor rates were charged by title: supervisor at $95.00/hour, data analyst at $57.00/hour, and field support at $28.50/hour.

Government representatives monitored on-site activity. All on-site activities were grouped into one of ten categories: initial setup/mobilization, daily setup/stop, calibration, collecting data, downtime due to break/lunch, downtime due to equipment failure, downtime due to equipment/data checks or maintenance, downtime due to weather, downtime due to demonstration site issue, or demobilization. See Appendix D for the daily activity log. See section 3.4 for a summary of field activities.

The standardized cost estimate associated with the labor needed to perform the field activities is presented in Table 9. Note that calibration time includes time spent in the Calibration Lanes as well as field calibrations. "Site survey time" includes daily setup/stop time, collecting data, breaks/lunch, downtime due to equipment/data checks or maintenance, downtime due to failure, and downtime due to weather.

## TABLE 9.   ON-SITE LABOR COSTS

|  | No. People | Hourly Wage | Hours | Cost |
|---|---|---|---|---|
| **Initial Setup** | | | | |
| Supervisor | 1 | $95.00 | 5.16 | $490.20 |
| Data Analyst | 1 | 57.00 | 5.16 | 294.12 |
| Field Support | 1 | 28.50 | 5.16 | 147.06 |
| SubTotal | | | | **$931.38** |
| **Calibration** | | | | |
| Supervisor | 1 | $95.00 | 4.00 | $380.00 |
| Data Analyst | 1 | 57.00 | 4.00 | 228.00 |
| Field Support | 1 | 28.50 | 4.00 | 114.00 |
| SubTotal | | | | **$722.00** |
| **Site Survey** | | | | |
| Supervisor | 1 | $95.00 | 57.25 | $5438.75 |
| Data Analyst | 1 | 57.00 | 57.25 | 3263.25 |
| Field Support | 1 | 28.50 | 57.25 | 1631.63 |
| SubTotal | | | | **$10,333.63** |

See notes at end of table.

TABLE 9 (CONT'D)

|  | No. People | Hourly Wage | Hours | Cost |
|---|---|---|---|---|
| Demobilization | | | | |
| Supervisor | 1 | $95.00 | 1.58 | $150.10 |
| Data Analyst | 1 | 57.00 | 1.58 | 90.06 |
| Field Support | 1 | 28.50 | 1.58 | 45.03 |
| Subtotal | | | | $285.19 |
| Total | | | | $12,272.20 |

Notes: Calibration time includes time spent in the Calibration Lanes as well as calibration before each data run.

Site Survey time includes daily setup/stop time, collecting data, breaks/lunch, downtime due to system maintenance, failure, and weather.

# SECTION 6. COMPARISON OF RESULTS TO BLIND GRID DEMONSTRATION (BASED ON FERROUS ONLY GROUND TRUTH)

## 6.1 SUMMARY OF RESULTS FROM BLIND GRID DEMONSTRATION

Table 10 shows the results from the Blind Grid survey conducted prior to surveying the Open Field during the same site visit in October of 2003. Due to the system utilizing magnetometer type sensors, all results presented in the following section have been based on performance scoring against the ferrous only ground truth anomalies. For more details on the Blind Grid survey results reference section 2.1.6.

### TABLE 10. SUMMARY OF BLIND GRID MAG ONLY RESULTS FOR THE TM-4 MAG (FERROUS ONLY)

| Metric | Overall | Standard | Nonstandard | By Size | | | By Depth, m | | |
|---|---|---|---|---|---|---|---|---|---|
| | | | | Small | Medium | Large | < 0.3 | 0.3 to <1 | >= 1 |
| RESPONSE STAGE | | | | | | | | | |
| $P_d$ | 0.65 | 0.75 | 0.50 | 0.60 | 0.70 | 0.80 | 0.75 | 0.70 | 0.40 |
| $P_d$ Low 90% Conf | 0.59 | 0.65 | 0.38 | 0.48 | 0.55 | 0.55 | 0.63 | 0.58 | 0.20 |
| $P_d$ Upper 90% Conf | 0.75 | 0.84 | 0.66 | 0.74 | 0.79 | 0.95 | 0.86 | 0.83 | 0.60 |
| $P_{fp}$ | 0.75 | - | - | - | - | - | 0.75 | 0.70 | 1.00 |
| $P_{fp}$ Low 90% Conf | 0.68 | - | - | - | - | - | 0.65 | 0.61 | 0.63 |
| $P_{fp}$ Upper 90% Conf | 0.80 | - | - | - | - | - | 0.83 | 0.81 | 1.00 |
| $P_{ba}$ | 0.10 | - | - | - | - | - | - | - | - |
| DISCRIMINATION STAGE | | | | | | | | | |
| $P_d$ | 0.65 | 0.75 | 0.40 | 0.55 | 0.65 | 0.80 | 0.70 | 0.70 | 0.40 |
| $P_d$ Low 90% Conf | 0.55 | 0.65 | 0.27 | 0.42 | 0.51 | 0.55 | 0.55 | 0.54 | 0.20 |
| $P_d$ Upper 90% Conf | 0.71 | 0.84 | 0.55 | 0.68 | 0.76 | 0.95 | 0.80 | 0.80 | 0.60 |
| $P_{fp}$ | 0.60 | - | - | - | - | - | 0.60 | 0.55 | 0.80 |
| $P_{fp}$ Low 90% Conf | 0.54 | - | - | - | - | - | 0.51 | 0.46 | 0.42 |
| $P_{fp}$ Upper 90% Conf | 0.67 | - | - | - | - | - | 0.71 | 0.68 | 0.98 |
| $P_{ba}$ | 0.05 | - | - | - | - | - | - | - | - |

## 6.2 COMPARISON OF ROC CURVES USING ALL ORDNANCE CATEGORIES

Figure 6 shows $P_d^{res}$ versus the respective $P_{fp}$ over all ordnance categories. Figure 7 shows $P_d^{disc}$ versus their respective $P_{fp}$ over all ordnance categories. Figure 7 uses horizontal lines to illustrate the performance of the demonstrator at the recommended discrimination threshold levels, defining the subset of targets the demonstrator would recommend digging based on discrimination. The ROC curves in this section are a sole reflection of the MAG only survey.
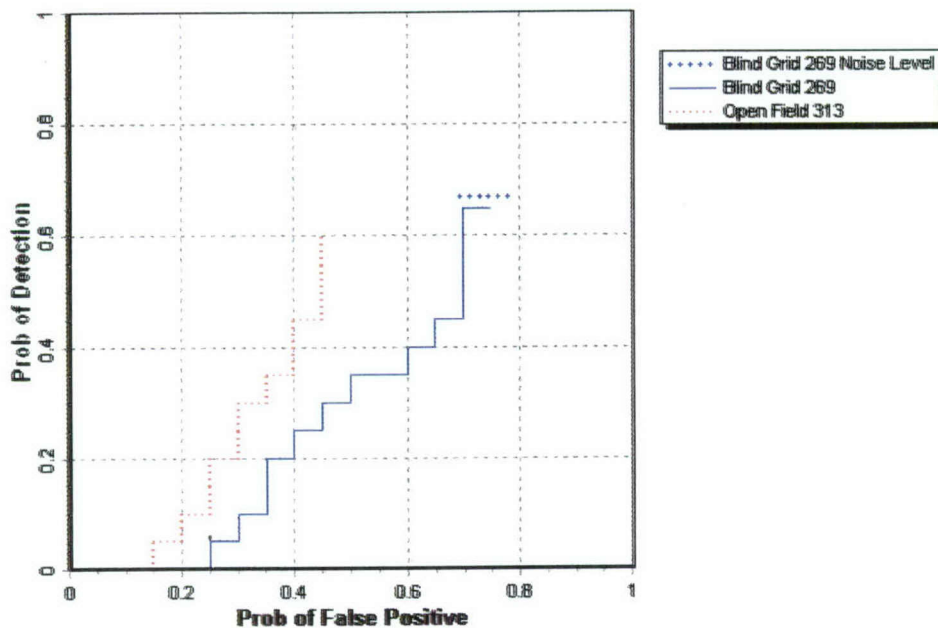
Figure 6.   TM-4 MAG $P_d^{res}$ stages versus the respective $P_{fp}$ over all ordnance categories combined.
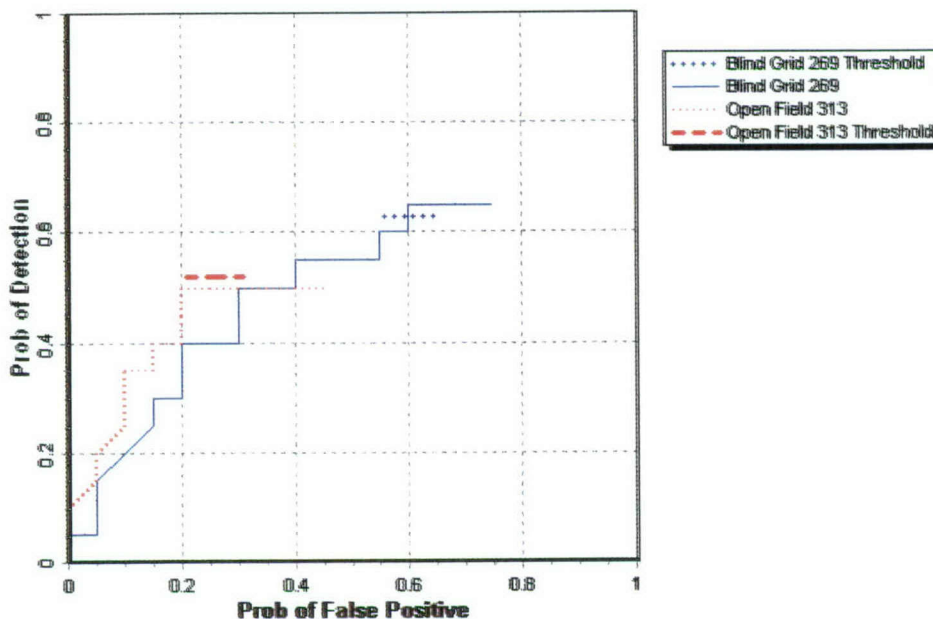


Figure 7.   TM-4 MAG $P_d^{disc}$ versus the respective $P_{fp}$ over all ordnance categories combined.

## 6.3 COMPARISON OF ROC CURVES USING ORDNANCE LARGER THAN 20 MM

Figure 8 shows the $P_d^{res}$ versus the respective probability of $P_{fp}$ over ordnance larger than 20 mm. Figure 9 shows $P_d^{disc}$ versus the respective $P_{fp}$ over ordnance larger than 20 mm. Figure 9 uses horizontal lines to illustrate the performance of the demonstrator at the recommended discrimination threshold levels, defining the subset of targets the demonstrator would recommend digging based on discrimination.
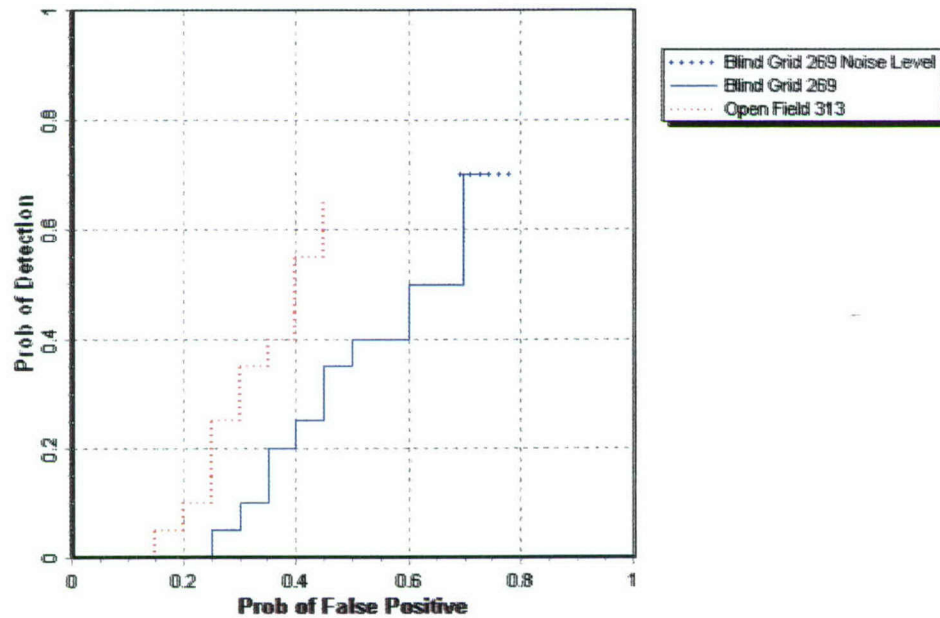


Figure 8.   TM-4 MAG $P_d^{res}$ versus the respective $P_{fp}$ for ordnance larger than 20 mm.
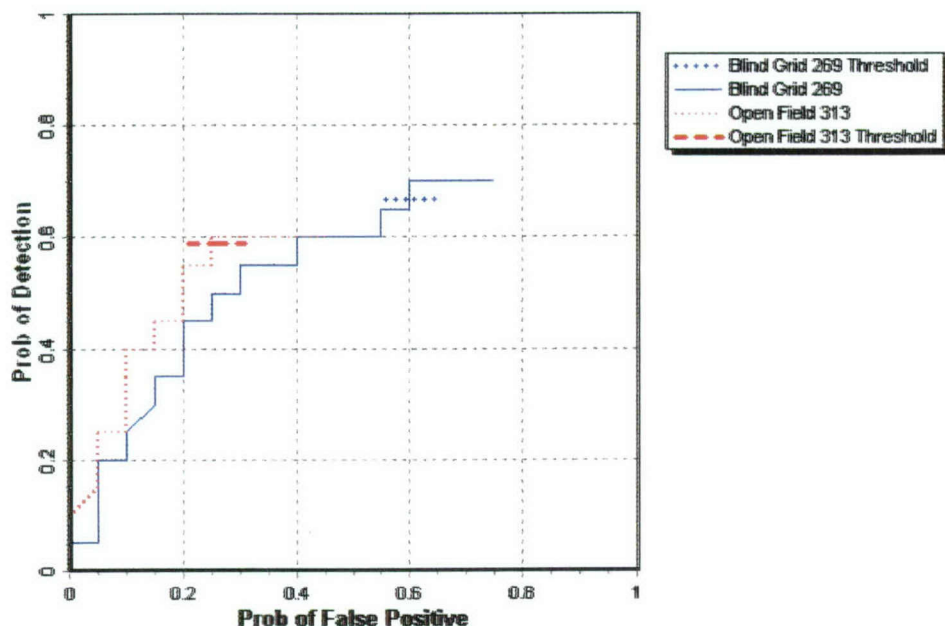
Figure 9.   TM-4 MAG $P_d^{disc}$ versus the respective $P_{fp}$ for ordnance larger than 20 mm.

## 6.4  STATISTICAL COMPARISONS

Statistical Chi-square significance tests were used to compare results between the Blind Grid and Open Field scenarios. The intent of the comparison is to determine if the feature introduced in each scenario has a degrading effect on the performance of the sensor system. However, any modifications in the UXO sensor system during the test, like changes in the processing or changes in the selection of the operating threshold, will also contribute to performance differences.

The Chi-square test for comparison between ratios was used at a significance level of 0.05 to compare Blind Grid to Open Field with regard to $P_d^{res}$, $P_d^{disc}$, $P_{fp}^{res}$ and $P_{fp}^{disc}$, Efficiency and Rejection Rate.  These results are presented in Table 11.  A detailed explanation and example of the Chi-square application is located in Appendix A.

**TABLE 11.   CHI-SQUARE RESULTS - BLIND GRID VERSUS OPEN FIELD**

| Metric | Small | Medium | Large | Overall |
|---|---|---|---|---|
| $P_d^{res}$ | Not Significant | Not Significant | Not Significant | Not Significant |
| $P_d^{disc}$ | Significant | Not Significant | Not Significant | Not Significant |
| $P_{fp}^{res}$ | Not Significant | Not Significant | Not Significant | Not Significant |
| $P_{fp}^{disc}$ | - | - | - | Significant |
| Efficiency | - | - | - | Significant |
| Rejection rate | - | - | - | Significant |

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# SECTION 7.  APPENDIXES

## APPENDIX A.  TERMS AND DEFINITIONS

GENERAL DEFINITIONS

Anomaly: Location of a system response deemed to warrant further investigation by the demonstrator for consideration as an emplaced ordnance item.

Detection: An anomaly location that is within $R_{halo}$ of an emplaced ordnance item.

Emplaced Ordnance: An ordnance item buried by the government at a specified location in the test site.

Emplaced Clutter: A clutter item (i.e., non-ordnance item) buried by the government at a specified location in the test site.

$R_{halo}$: A pre-determined radius about the periphery of an emplaced item (clutter or ordnance) within which a location identified by the demonstrator as being of interest is considered to be a response from that item.  If multiple declarations lie within $R_{halo}$ of any item (clutter or ordnance), the declaration with the highest signal output within the $R_{halo}$ will be utilized.  For the purpose of this program, a circular halo 0.5 meters in radius will be placed around the center of the object for all clutter and ordnance items less than 0.6 meters in length.  When ordnance items are longer than 0.6 meters, the halo becomes an ellipse where the minor axis remains 1 meter and the major axis is equal to the length of the ordnance plus 1 meter.

Small Ordnance: Caliber of ordnance less than or equal to 40 mm (includes 20-mm projectile, 40-mm projectile, submunitions BLU-26, BLU-63, and M42).

Medium Ordnance: Caliber of ordnance greater than 40 mm and less than or equal to 81 mm (includes 57-mm projectile, 60-mm mortar, 2.75 in. Rocket, MK118 Rockeye, 81-mm mortar).

Large Ordnance: Caliber of ordnance greater than 81 mm (includes 105-mm HEAT, 105-mm projectile, 155-mm projectile, 500-pound bomb).

Shallow:  Items buried less than 0.3 meter below ground surface.

Medium: Items buried greater than or equal to 0.3 meter and less than 1 meter below ground surface.

Deep:  Items buried greater than or equal to 1 meter below ground surface.

Response Stage Noise Level:  The level that represents the point below which anomalies are not considered detectable.  Demonstrators are required to provide the recommended noise level for the Blind Grid test area.

Discrimination Stage Threshold: The demonstrator selected threshold level that they believe provides optimum performance of the system by retaining all detectable ordnance and rejecting the maximum amount of clutter. This level defines the subset of anomalies the demonstrator would recommend digging based on discrimination.

Binomially Distributed Random Variable: A random variable of the type which has only two possible outcomes, say success and failure, is repeated for n independent trials with the probability p of success and the probability 1-p of failure being the same for each trial. The number of successes x observed in the n trials is an estimate of p and is considered to be a binomially distributed random variable.

RESPONSE AND DISCRIMINATION STAGE DATA

The scoring of the demonstrator's performance is conducted in two stages. These two stages are termed the RESPONSE STAGE and DISCRIMINATION STAGE. For both stages, the probability of detection ($P_d$) and the false alarms are reported as receiver operating characteristic (ROC) curves. False alarms are divided into those anomalies that correspond to emplaced clutter items, measuring the probability of false positive ($P_{fp}$) and those that do not correspond to any known item, termed background alarms.

The RESPONSE STAGE scoring evaluates the ability of the system to detect emplaced targets without regard to ability to discriminate ordnance from other anomalies. For the RESPONSE STAGE, the demonstrator provides the scoring committee with the location and signal strength of all anomalies that the demonstrator has deemed sufficient to warrant further investigation and/or processing as potential emplaced ordnance items. This list is generated with minimal processing (e.g., this list will include all signals above the system noise threshold). As such, it represents the most inclusive list of anomalies.

The DISCRIMINATION STAGE evaluates the demonstrator's ability to correctly identify ordnance as such, and to reject clutter. For the same locations as in the RESPONSE STAGE anomaly list, the DISCRIMINATION STAGE list contains the output of the algorithms applied in the discrimination-stage processing. This list is prioritized based on the demonstrator's determination that an anomaly location is likely to contain ordnance. Thus, higher output values are indicative of higher confidence that an ordnance item is present at the specified location. For electronic signal processing, priority ranking is based on algorithm output. For other systems, priority ranking is based on human judgment. The demonstrator also selects the threshold that the demonstrator believes will provide "optimum" system performance, (i.e., that retains all the detected ordnance and rejects the maximum amount of clutter).

Note:  The two lists provided by the demonstrator contain identical numbers of potential target locations. They differ only in the priority ranking of the declarations.

RESPONSE STAGE DEFINITIONS

Response Stage Probability of Detection ($P_d^{res}$): $P_d^{res}$ = (No. of response-stage detections)/ (No. of emplaced ordnance in the test site).

Response Stage False Positive ($fp^{res}$): An anomaly location that is within $R_{halo}$ of an emplaced clutter item.

Response Stage Probability of False Positive ($P_{fp}^{res}$): $P_{fp}^{res}$ = (No. of response-stage false positives)/(No. of emplaced clutter items).

Response Stage Background Alarm ($ba^{res}$): An anomaly in a blind grid cell that contains neither emplaced ordnance nor an emplaced clutter item. An anomaly location in the open field or scenarios that is outside $R_{halo}$ of any emplaced ordnance or emplaced clutter item.

Response Stage Probability of Background Alarm ($P_{ba}^{res}$): Blind Grid only: $P_{ba}^{res}$ = (No. of response-stage background alarms)/(No. of empty grid locations).

Response Stage Background Alarm Rate ($BAR^{res}$): Open Field only: $BAR^{res}$ = (No. of response-stage background alarms)/(arbitrary constant).

Note that the quantities $P_d^{res}$, $P_{fp}^{res}$, $P_{ba}^{res}$, and $BAR^{res}$ are functions of $t^{res}$, the threshold applied to the response-stage signal strength. These quantities can therefore be written as $P_d^{res}(t^{res})$, $P_{fp}^{res}(t^{res})$, $P_{ba}^{res}(t^{res})$, and $BAR^{res}(t^{res})$.

DISCRIMINATION STAGE DEFINITIONS

Discrimination: The application of a signal processing algorithm or human judgment to response-stage data that discriminates ordnance from clutter. Discrimination should identify anomalies that the demonstrator has high confidence correspond to ordnance, as well as those that the demonstrator has high confidence correspond to nonordnance or background returns. The former should be ranked with highest priority and the latter with lowest.

Discrimination Stage Probability of Detection ($P_d^{disc}$): $P_d^{disc}$ = (No. of discrimination-stage detections)/(No. of emplaced ordnance in the test site).

Discrimination Stage False Positive ($fp^{disc}$): An anomaly location that is within $R_{halo}$ of an emplaced clutter item.

Discrimination Stage Probability of False Positive ($P_{fp}^{disc}$): $P_{fp}^{disc}$ = (No. of discrimination stage false positives)/(No. of emplaced clutter items).

Discrimination Stage Background Alarm ($ba^{disc}$): An anomaly in a blind grid cell that contains neither emplaced ordnance nor an emplaced clutter item. An anomaly location in the open field or scenarios that is outside $R_{halo}$ of any emplaced ordnance or emplaced clutter item.

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Discrimination Stage Probability of Background Alarm ($P_{ba}^{disc}$): $P_{ba}^{disc}$ = (No. of discrimination-stage background alarms)/(No. of empty grid locations).

Discrimination Stage Background Alarm Rate ($BAR^{disc}$): $BAR^{disc}$ = (No. of discrimination-stage background alarms)/(arbitrary constant).

Note that the quantities $P_d^{disc}$, $P_{fp}^{disc}$, $P_{ba}^{disc}$, and $BAR^{disc}$ are functions of $t^{disc}$, the threshold applied to the discrimination-stage signal strength. These quantities can therefore be written as $P_d^{disc}(t^{disc})$, $P_{fp}^{disc}(t^{disc})$, $P_{ba}^{disc}(t^{disc})$, and $BAR^{disc}(t^{disc})$.

RECEIVER-OPERATING CHARACERISTIC (ROC) CURVES

ROC curves at both the response and discrimination stages can be constructed based on the above definitions. The ROC curves plot the relationship between $P_d$ versus $P_{fp}$ and $P_d$ versus BAR or $P_{ba}$ as the threshold applied to the signal strength is varied from its minimum ($t_{min}$) to its maximum ($t_{max}$) value.[1] Figure A-1 shows how $P_d$ versus $P_{fp}$ and $P_d$ versus BAR are combined into ROC curves. Note that the "res" and "disc" superscripts have been suppressed from all the variables for clarity.
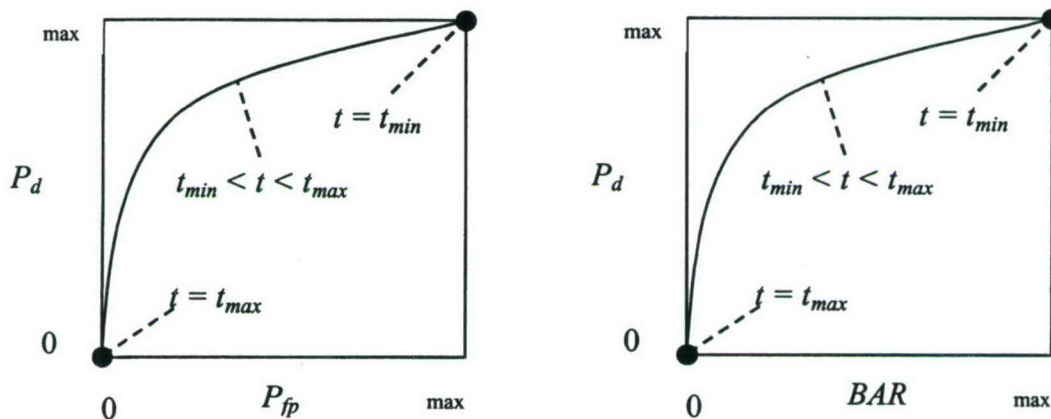


Figure A-1.  ROC curves for open field testing. Each curve applies to both the response and discrimination stages.

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[1]Strictly speaking, ROC curves plot the $P_d$ versus $P_{ba}$ over a pre-determined and fixed number of detection opportunities (some of the opportunities are located over ordnance and others are located over clutter or blank spots). In an open field scenario, each system suppresses its signal strength reports until some bare-minimum signal response is received by the system. Consequently, the open field ROC curves do not have information from low signal-output locations, and, furthermore, different contractors report their signals over a different set of locations on the ground. These ROC curves are thus not true to the strict definition of ROC curves as defined in textbooks on detection theory. Note, however, that the ROC curves obtained in the Blind Grid test sites are true ROC curves.

## METRICS TO CHARACTERIZE THE DISCRIMINATION STAGE

The demonstrator is also scored on efficiency and rejection ratio, which measure the effectiveness of the discrimination stage processing. The goal of discrimination is to retain the greatest number of ordnance detections from the anomaly list, while rejecting the maximum number of anomalies arising from nonordnance items. The efficiency measures the amount of detected ordnance retained by the discrimination, while the rejection ratio measures the fraction of false alarms rejected. Both measures are defined relative to the entire response list, i.e., the maximum ordnance detectable by the sensor and its accompanying false positive rate or background alarm rate.

Efficiency (E): $E = P_d^{disc}(t^{disc})/P_d^{res}(t_{min}^{res})$; Measures (at a threshold of interest), the degree to which the maximum theoretical detection performance of the sensor system (as determined by the response stage tmin) is preserved after application of discrimination techniques. Efficiency is a number between 0 and 1. An efficiency of 1 implies that all of the ordnance initially detected in the response stage was retained at the specified threshold in the discrimination stage, $t^{disc}$.

False Positive Rejection Rate ($R_{fp}$): $R_{fp} = 1 - [P_{fp}^{disc}(t^{disc})/P_{fp}^{res}(t_{min}^{res})]$; Measures (at a threshold of interest), the degree to which the sensor system's false positive performance is improved over the maximum false positive performance (as determined by the response stage tmin). The rejection rate is a number between 0 and 1. A rejection rate of 1 implies that all emplaced clutter initially detected in the response stage were correctly rejected at the specified threshold in the discrimination stage.

Background Alarm Rejection Rate ($R_{ba}$):

Blind Grid: $R_{ba} = 1 - [P_{ba}^{disc}(t^{disc})/P_{ba}^{res}(t_{min}^{res})]$.
Open Field: $R_{ba} = 1 - [BAR^{disc}(t^{disc})/BAR^{res}(t_{min}^{res})])$.

Measures the degree to which the discrimination stage correctly rejects background alarms initially detected in the response stage. The rejection rate is a number between 0 and 1. A rejection rate of 1 implies that all background alarms initially detected in the response stage were rejected at the specified threshold in the discrimination stage.

## CHI-SQUARE COMPARISON EXPLANATION:

The Chi-square test for differences in probabilities (or 2 x 2 contingency table) is used to analyze two samples drawn from two different populations to see if both populations have the same or different proportions of elements in a certain category. More specifically, two random samples are drawn, one from each population, to test the null hypothesis that the probability of event A (some specified event) is the same for both populations (ref 3).

A 2 x 2 contingency table is used in the Standardized UXO Technology Demonstration Site Program to determine if there is reason to believe that the proportion of ordnance correctly detected/discriminated by demonstrator X's system is significantly degraded by the more challenging terrain feature introduced. The test statistic of the 2 x 2 contingency table is the

Chi-square distribution with one degree of freedom. Since an association between the more challenging terrain feature and relatively degraded performance is sought, a one-sided test is performed. A significance level of 0.05 is chosen which sets a critical decision limit of 2.71 from the Chi-square distribution with one degree of freedom. It is a critical decision limit because if the test statistic calculated from the data exceeds this value, the two proportions tested will be considered significantly different. If the test statistic calculated from the data is less than this value, the two proportions tested will be considered not significantly different.

An exception must be applied when either a 0 or 100 percent success rate occurs in the sample data. The Chi-square test cannot be used in these instances. Instead, Fischer's test is used and the critical decision limit for one-sided tests is the chosen significance level, which in this case is 0.05. With Fischer's test, if the test statistic is less than the critical value, the proportions are considered to be significantly different.

Standardized UXO Technology Demonstration Site examples, where blind grid results are compared to those from the open field and open field results are compared to those from one of the scenarios, follow. It should be noted that a significant result does not prove a cause and effect relationship exists between the two populations of interest; however, it does serve as a tool to indicate that one data set has experienced a degradation in system performance at a large enough level than can be accounted for merely by chance or random variation. Note also that a result that is not significant indicates that there is not enough evidence to declare that anything more than chance or random variation within the same population is at work between the two data sets being compared.

Demonstrator X achieves the following overall results after surveying each of the three progressively more difficult areas using the same system (results indicate the number of ordnance detected divided by the number of ordnance emplaced):

| | Blind Grid | Open Field | Moguls |
|---|---|---|---|
| $P_d^{res}$ | 100/100 = 1.0 | 8/10 = .80 | 20/33 = .61 |
| $P_d^{disc}$ | 80/100 = 0.80 | 6/10 = .60 | 8/33 = .24 |

$P_d^{res}$: BLIND GRID versus OPEN FIELD. Using the example data above to compare probabilities of detection in the response stage, all 100 ordnance out of 100 emplaced ordnance items were detected in the blind grid while 8 ordnance out of 10 emplaced were detected in the open field. Fischer's test must be used since a 100 percent success rate occurs in the data. Fischer's test uses the four input values to calculate a test statistic of 0.0075 that is compared against the critical value of 0.05. Since the test statistic is less than the critical value, the smaller response stage detection rate (0.80) is considered to be significantly less at the 0.05 level of significance. While a significant result does not prove a cause and effect relationship exists between the change in survey area and degradation in performance, it does indicate that the detection ability of demonstrator X's system seems to have been degraded in the open field relative to results from the blind grid using the same system.

$P_d^{disc}$: BLIND GRID versus OPEN FIELD. Using the example data above to compare probabilities of detection in the discrimination stage, 80 out of 100 emplaced ordnance items were correctly discriminated as ordnance in blind grid testing while 6 ordnance out of 10 emplaced were correctly discriminated as such in open field-testing. Those four values are used to calculate a test statistic of 1.12. Since the test statistic is less than the critical value of 2.71, the two discrimination stage detection rates are considered to be not significantly different at the 0.05 level of significance.

$P_d^{res}$: OPEN FIELD versus MOGULS. Using the example data above to compare probabilities of detection in the response stage, 8 out of 10 and 20 out of 33 are used to calculate a test statistic of 0.56. Since the test statistic is less than the critical value of 2.71, the two response stage detection rates are considered to be not significantly different at the 0.05 level of significance.

$P_d^{disc}$: OPEN FIELD versus MOGULS. Using the example data above to compare probabilities of detection in the discrimination stage, 6 out of 10 and 8 out of 33 are used to calculate a test statistic of 2.98. Since the test statistic is greater than the critical value of 2.71, the smaller discrimination stage detection rate is considered to be significantly less at the 0.05 level of significance. While a significant result does not prove a cause and effect relationship exists between the change in survey area and degradation in performance, it does indicate that the ability of demonstrator X to correctly discriminate seems to have been degraded by the mogul terrain relative to results from the flat open field using the same system.

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# APPENDIX B. DAILY WEATHER LOGS

## TABLE B-1. WEATHER LOG

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/13/2003 00:00:00 | 63 | 63.9 | 62.4 | 86.5 | 0 |
| 10/13/2003 01:00:00 | 64 | 64.9 | 62.8 | 80.2 | 0 |
| 10/13/2003 02:00:00 | 63 | 64.5 | 61.6 | 71.39 | 0 |
| 10/13/2003 03:00:00 | 60.8 | 62.1 | 59.8 | 70.15 | 0 |
| 10/13/2003 04:00:00 | 59.1 | 60.3 | 57.7 | 70.46 | 0 |
| 10/13/2003 05:00:00 | 55.3 | 57.8 | 53 | 78.39 | 0 |
| 10/13/2003 06:00:00 | 55.1 | 56.3 | 52.8 | 76.67 | 0 |
| 10/13/2003 07:00:00 | 51.6 | 53.2 | 50.3 | 86.3 | 0 |
| 10/13/2003 08:00:00 | 55.8 | 60.6 | 51.2 | 81.9 | 0 |
| 10/13/2003 09:00:00 | 62 | 63.3 | 60.5 | 62.18 | 0 |
| 10/13/2003 10:00:00 | 64.6 | 65.9 | 63 | 54.9 | 0 |
| 10/13/2003 11:00:00 | 66.7 | 67.7 | 65.5 | 48.23 | 0 |
| 10/13/2003 12:00:00 | 68.6 | 70.2 | 67.5 | 44.38 | 0 |
| 10/13/2003 13:00:00 | 70.5 | 71.5 | 69.7 | 42.08 | 0 |
| 10/13/2003 14:00:00 | 72 | 73 | 71.3 | 39.13 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/13/2003 15:00:00 | 72.5 | 73.2 | 71.7 | 37.51 | 0 |
| 10/13/2003 16:00:00 | 72.9 | 74.1 | 71.9 | 37.03 | 0 |
| 10/13/2003 17:00:00 | 70.5 | 73.1 | 67.7 | 44.83 | 0 |
| 10/13/2003 18:00:00 | 63.6 | 67.7 | 60.4 | 64.13 | 0 |
| 10/13/2003 19:00:00 | 58.2 | 60.8 | 56.1 | 81.3 | 0 |
| 10/13/2003 20:00:00 | 54.8 | 56.5 | 52.6 | 89.6 | 0 |
| 10/13/2003 21:00:00 | 52.6 | 53.3 | 51.8 | 95.1 | 0 |
| 10/13/2003 22:00:00 | 51.7 | 53 | 50.2 | 96.6 | 0 |
| 10/13/2003 23:00:00 | 50.1 | 51.3 | 48.6 | 97.5 | 0 |
| 10/14/2003 00:00:00 | 49.5 | 50.6 | 48.5 | 97.7 | 0 |
| 10/14/2003 01:00:00 | 48.4 | 49 | 47.9 | 98.1 | 0 |
| 10/14/2003 02:00:00 | 48.1 | 48.9 | 47.6 | 98.5 | 0 |
| 10/14/2003 03:00:00 | 47.8 | 48.6 | 47.2 | 98.6 | 0 |
| 10/14/2003 04:00:00 | 48.5 | 49.8 | 47.4 | 98.7 | 0 |
| 10/14/2003 05:00:00 | 48.9 | 49.7 | 48.4 | 98.6 | 0 |
| 10/14/2003 06:00:00 | 49.2 | 49.8 | 48.6 | 98.2 | 0 |
| 10/14/2003 07:00:00 | 50.2 | 51.4 | 49.5 | 98.4 | 0 |
| 10/14/2003 08:00:00 | 23.5 | 57.6 | 49.6 | 97.8 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/14/2003 09:00:00 | 58.2 | 58.8 | 57 | 93.2 | 0 |
| 10/14/2003 10:00:00 | 59.4 | 61.5 | 58.2 | 90.9 | 0 |
| 10/14/2003 11:00:00 | 62.1 | 63.4 | 60.9 | 76.27 | 0 |
| 10/14/2003 12:00:00 | 64.8 | 66.8 | 63.1 | 68.16 | 0 |
| 10/14/2003 13:00:00 | 66.3 | 66.8 | 65.8 | 62.79 | 0 |
| 10/14/2003 14:00:00 | 67.1 | 67.9 | 66 | 65.61 | 0 |
| 10/14/2003 15:00:00 | 67.4 | 67.9 | 66.9 | 61.98 | 0 |
| 10/14/2003 16:00:00 | 66.9 | 67.7 | 65.6 | 62.65 | 0 |
| 10/14/2003 17:00:00 | 66.6 | 67.1 | 65.9 | 64.35 | 0 |
| 10/14/2003 18:00:00 | 66.7 | 67.2 | 66 | 59.18 | 0 |
| 10/14/2003 19:00:00 | 64.4 | 66.3 | 61.6 | 66.71 | 0.01 |
| 10/14/2003 20:00:00 | 60.9 | 62.3 | 59.6 | 85.4 | 0.06 |
| 10/14/2003 21:00:00 | 59.8 | 60.9 | 59.1 | 96.7 | 0.54 |
| 10/14/2003 22:00:00 | 60.6 | 62.6 | 58.8 | 97.3 | 0.58 |
| 10/14/2003 23:00:00 | 59 | 59.4 | 58.6 | 97.4 | 0.09 |
| 10/15/2003 00:00:00 | 59.4 | 59.8 | 58.9 | 95.9 | 0.05 |
| 10/15/2003 01:00:00 | 58.6 | 59.4 | 58.2 | 95.2 | 0.06 |
| 10/15/2003 02:00:00 | 58.4 | 59 | 57.8 | 95.9 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/15/2003 03:00:00 | 58.2 | 59.6 | 56.6 | 84 | 0 |
| 10/15/2003 04:00:00 | 56.9 | 57.7 | 56.3 | 76.63 | 0 |
| 10/15/2003 05:00:00 | 57.5 | 58.1 | 56.6 | 68.15 | 0 |
| 10/15/2003 06:00:00 | 56.9 | 57.5 | 56.3 | 68.6 | 0 |
| 10/15/2003 07:00:00 | 57.1 | 58.4 | 56.4 | 67.96 | 0 |
| 10/15/2003 08:00:00 | 59.3 | 61.1 | 57.9 | 62.94 | 0 |
| 10/15/2003 09:00:00 | 61.1 | 61.8 | 60.2 | 56.07 | 0 |
| 10/15/2003 10:00:00 | 61.6 | 62.8 | 60.4 | 49.26 | 0 |
| 10/15/2003 11:00:00 | 61.6 | 63.6 | 60.6 | 45.58 | 0 |
| 10/15/2003 12:00:00 | 62.1 | 63.1 | 61.4 | 37.39 | 0 |
| 10/15/2003 13:00:00 | 62.3 | 63.2 | 61.6 | 34.49 | 0 |
| 10/15/2003 14:00:00 | 62.3 | 63.4 | 61.3 | 35.6 | 0 |
| 10/15/2003 15:00:00 | 62.1 | 62.9 | 60.9 | 34.25 | 0 |
| 10/15/2003 16:00:00 | 61.9 | 62.6 | 61.4 | 32 | 0 |
| 10/15/2003 17:00:00 | 60.9 | 62.1 | 59.5 | 32.13 | 0 |
| 10/15/2003 18:00:00 | 57.9 | 59.7 | 56.2 | 38.03 | 0 |
| 10/15/2003 19:00:00 | 54 | 56.6 | 51.4 | 48.83 | 0 |
| 10/15/2003 20:00:00 | 51.5 | 52.3 | 50.3 | 56.15 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/15/2003 21:00:00 | 49.4 | 50.7 | 48.4 | 62.51 | 0 |
| 10/15/2003 22:00:00 | 49.1 | 51 | 46.7 | 61.25 | 0 |
| 10/15/2003 23:00:00 | 46.1 | 47.1 | 44.7 | 70.62 | 0 |
| 10/16/2003 00:00:00 | 45.3 | 47.6 | 42.9 | 74.08 | 0 |
| 10/16/2003 01:00:00 | 45 | 46.1 | 43.3 | 76.85 | 0 |
| 10/16/2003 02:00:00 | 43.2 | 44.3 | 42.5 | 85.9 | 0 |
| 10/16/2003 03:00:00 | 44 | 45.3 | 43 | 81.6 | 0 |
| 10/16/2003 04:00:00 | 45 | 46.3 | 44.1 | 79.04 | 0 |
| 10/16/2003 05:00:00 | 45.1 | 46.3 | 43.7 | 79.29 | 0 |
| 10/16/2003 06:00:00 | 44.6 | 45.2 | 43.9 | 80.2 | 0 |
| 10/16/2003 07:00:00 | 45 | 46.4 | 44.1 | 78.73 | 0 |
| 10/16/2003 08:00:00 | 49.5 | 52.4 | 46.3 | 73.12 | 0 |
| 10/16/2003 09:00:00 | 55.3 | 58 | 52.1 | 61.45 | 0 |
| 10/16/2003 10:00:00 | 60.4 | 62 | 57.8 | 49.01 | 0 |
| 10/16/2003 11:00:00 | 63.1 | 64.9 | 61.6 | 44.5 | 0 |
| 10/16/2003 12:00:00 | 65.9 | 67.1 | 64.3 | 40.73 | 0 |
| 10/16/2003 13:00:00 | 67.4 | 68.6 | 66 | 38.93 | 0 |
| 10/16/2003 14:00:00 | 68.6 | 70.2 | 67.2 | 38.51 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/16/2003 15:00:00 | 69.5 | 70 | 69 | 37.41 | 0 |
| 10/16/2003 16:00:00 | 68.3 | 69.1 | 66.3 | 42.96 | 0 |
| 10/16/2003 17:00:00 | 66 | 66.9 | 65 | 48.21 | 0 |
| 10/16/2003 18:00:00 | 63.8 | 65.2 | 62.8 | 54.51 | 0 |
| 10/16/2003 19:00:00 | 61.1 | 63.2 | 59.5 | 54.05 | 0 |
| 10/16/2003 20:00:00 | 57.7 | 59.8 | 55.9 | 60.26 | 0 |
| 10/16/2003 21:00:00 | 54 | 56.2 | 52.7 | 72.68 | 0 |
| 10/16/2003 22:00:00 | 53.2 | 53.6 | 52.7 | 79.79 | 0 |
| 10/16/2003 23:00:00 | 53.5 | 54.5 | 52.9 | 81.2 | 0 |
| 10/17/2003 00:00:00 | 52.7 | 53.4 | 52 | 84.5 | 0 |
| 10/17/2003 01:00:00 | 51.4 | 52.8 | 50.1 | 88.4 | 0 |
| 10/17/2003 02:00:00 | 50.9 | 51.3 | 50.3 | 91.9 | 0 |
| 10/17/2003 03:00:00 | 50.5 | 51.7 | 49.1 | 90.6 | 0 |
| 10/17/2003 04:00:00 | 50.3 | 51.2 | 49.1 | 89.5 | 0 |
| 10/17/2003 05:00:00 | 50.5 | 51.2 | 49.6 | 87.9 | 0 |
| 10/17/2003 06:00:00 | 50 | 51 | 48.5 | 87.7 | 0 |
| 10/17/2003 07:00:00 | 49.6 | 50.8 | 48.6 | 90.5 | 0 |
| 10/17/2003 08:00:00 | 51.8 | 53 | 50.6 | 86.9 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/17/2003 09:00:00 | 54.1 | 55.8 | 52.5 | 82 | 0 |
| 10/17/2003 10:00:00 | 55.4 | 56 | 54.7 | 75.27 | 0 |
| 10/17/2003 11:00:00 | 55.8 | 56.4 | 55.3 | 73.27 | 0 |
| 10/17/2003 12:00:00 | 55.6 | 56.3 | 55.2 | 71.2 | 0 |
| 10/17/2003 13:00:00 | 56.6 | 57.7 | 55.7 | 69.08 | 0 |
| 10/17/2003 14:00:00 | 58.1 | 59 | 57.3 | 66.98 | 0 |
| 10/17/2003 15:00:00 | 57.6 | 58.4 | 56.8 | 68.63 | 0 |
| 10/17/2003 16:00:00 | 56.8 | 57.2 | 56.5 | 70.86 | 0 |
| 10/17/2003 17:00:00 | 55.3 | 56.7 | 54.2 | 80.1 | 0 |
| 10/17/2003 18:00:00 | 53.6 | 54.7 | 52.8 | 85.7 | 0 |
| 10/17/2003 19:00:00 | 52.2 | 53.3 | 51.1 | 88.5 | 0.01 |
| 10/17/2003 20:00:00 | 50.7 | 51.5 | 49.7 | 92.8 | 0.02 |
| 10/17/2003 21:00:00 | 49.3 | 50.2 | 48.8 | 94.7 | 0.02 |
| 10/17/2003 22:00:00 | 48.8 | 49.3 | 48.4 | 93.5 | 0 |
| 10/17/2003 23:00:00 | 48.3 | 48.6 | 47.8 | 93.3 | 0 |
| 10/18/2003 00:00:00 | 48.1 | 48.4 | 47.8 | 94 | 0 |
| 10/18/2003 01:00:00 | 48.1 | 48.4 | 47.8 | 94.7 | 0 |
| 10/18/2003 02:00:00 | 47.4 | 48.3 | 46.4 | 94.9 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/18/2003 03:00:00 | 46 | 46.7 | 44.9 | 96.3 | 0 |
| 10/18/2003 04:00:00 | 44.8 | 45.3 | 43.7 | 97.6 | 0 |
| 10/18/2003 05:00:00 | 44.8 | 45.4 | 44.1 | 97.9 | 0 |
| 10/18/2003 06:00:00 | 44.3 | 44.8 | 43.8 | 98.5 | 0 |
| 10/18/2003 07:00:00 | 44.2 | 44.8 | 43.8 | 98.7 | 0 |
| 10/18/2003 08:00:00 | 45.4 | 48.3 | 43.7 | 98.6 | 0 |
| 10/18/2003 09:00:00 | 49.8 | 51.9 | 47.4 | 87.3 | 0 |
| 10/18/2003 10:00:00 | 53.3 | 55 | 51.2 | 70.82 | 0 |
| 10/18/2003 11:00:00 | 56 | 57.2 | 54.5 | 53.7 | 0 |
| 10/18/2003 12:00:00 | 56.9 | 57.9 | 55.9 | 48.82 | 0 |
| 10/18/2003 13:00:00 | 58.6 | 59.7 | 57.6 | 40.83 | 0 |
| 10/18/2003 14:00:00 | 58.6 | 59.7 | 57.2 | 37.97 | 0 |
| 10/18/2003 15:00:00 | 59 | 60.2 | 57.9 | 39.36 | 0 |
| 10/18/2003 16:00:00 | 58.8 | 59.8 | 58.2 | 39.33 | 0 |
| 10/18/2003 17:00:00 | 57.4 | 58.6 | 56.2 | 41.5 | 0 |
| 10/18/2003 18:00:00 | 52 | 56.5 | 48.7 | 61.14 | 0 |
| 10/18/2003 19:00:00 | 47.2 | 49.8 | 44.7 | 79.42 | 0 |
| 10/18/2003 20:00:00 | 44.1 | 45 | 42.9 | 90.4 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/18/2003 21:00:00 | 42.5 | 43.5 | 41.1 | 94.2 | 0 |
| 10/18/2003 22:00:00 | 41.9 | 42.3 | 41.2 | 96.5 | 0 |
| 10/18/2003 23:00:00 | 41.5 | 42.3 | 40.9 | 96.7 | 0 |
| 10/19/2003 00:00:00 | 41.4 | 41.8 | 41 | 97.7 | 0 |
| 10/19/2003 01:00:00 | 42.4 | 43.4 | 41.3 | 97.9 | 0 |
| 10/19/2003 02:00:00 | 44 | 44.8 | 43.1 | 96.8 | 0 |
| 10/19/2003 03:00:00 | 45.4 | 46.3 | 44.6 | 95.9 | 0 |
| 10/19/2003 04:00:00 | 46.3 | 47 | 45.8 | 95.4 | 0 |
| 10/19/2003 05:00:00 | 47.1 | 48.3 | 46.4 | 96.3 | 0 |
| 10/19/2003 06:00:00 | 50.2 | 51 | 48.3 | 80.5 | 0 |
| 10/19/2003 07:00:00 | 51.7 | 52.6 | 50.8 | 75.4 | 0 |
| 10/19/2003 08:00:00 | 53 | 53.7 | 52.1 | 67.44 | 0 |
| 10/19/2003 09:00:00 | 54.4 | 55.6 | 52.7 | 67.01 | 0 |
| 10/19/2003 10:00:00 | 57 | 59.9 | 54.6 | 61.51 | 0 |
| 10/19/2003 11:00:00 | 62.4 | 63.8 | 59.6 | 53.53 | 0 |
| 10/19/2003 12:00:00 | 63.4 | 65.3 | 62.2 | 48.72 | 0 |
| 10/19/2003 13:00:00 | 65.1 | 66.3 | 63.6 | 44.24 | 0 |
| 10/19/2003 14:00:00 | 65.6 | 67.1 | 64.2 | 41.7 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/19/2003 15:00:00 | 65.6 | 66.4 | 64.1 | 38.45 | 0 |
| 10/19/2003 16:00:00 | 64.9 | 65.6 | 64 | 38.83 | 0 |
| 10/19/2003 17:00:00 | 63.4 | 64.5 | 61.8 | 41.49 | 0 |
| 10/19/2003 18:00:00 | 58.6 | 62 | 56.2 | 54.36 | 0 |
| 10/19/2003 19:00:00 | 53.5 | 56.7 | 49.8 | 69.72 | 0 |
| 10/19/2003 20:00:00 | 49.9 | 52 | 48.5 | 79.79 | 0 |
| 10/19/2003 21:00:00 | 47.8 | 50.4 | 45.3 | 86 | 0 |
| 10/19/2003 22:00:00 | 46.1 | 48.8 | 44.9 | 88.3 | 0 |
| 10/19/2003 23:00:00 | 47.2 | 49.1 | 44.8 | 80 | 0 |
| 10/20/2003 00:00:00 | 47.3 | 48.3 | 46.3 | 79.55 | 0 |
| 10/20/2003 01:00:00 | 46.3 | 47.5 | 45.1 | 81.4 | 0 |
| 10/20/2003 02:00:00 | 45.6 | 46.5 | 44.9 | 82.2 | 0 |
| 10/20/2003 03:00:00 | 44.2 | 46 | 41.5 | 85.4 | 0 |
| 10/20/2003 04:00:00 | 41 | 41.8 | 40.1 | 95.7 | 0 |
| 10/20/2003 05:00:00 | 40.5 | 42.1 | 38.8 | 96.4 | 0 |
| 10/20/2003 06:00:00 | 39.2 | 39.9 | 38.1 | 97.7 | 0 |
| 10/20/2003 07:00:00 | 38.7 | 39.8 | 37.8 | 98.5 | 0 |
| 10/20/2003 08:00:00 | 45 | 49.5 | 39.4 | 92.6 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/20/2003 09:00:00 | 50.9 | 52.2 | 49.3 | 78.03 | 0 |
| 10/20/2003 10:00:00 | 53.8 | 55.6 | 51.9 | 67.64 | 0 |
| 10/20/2003 11:00:00 | 55.7 | 56.6 | 54.7 | 65.53 | 0 |
| 10/20/2003 12:00:00 | 58.3 | 60.3 | 56.5 | 59.89 | 0 |
| 10/20/2003 13:00:00 | 60.7 | 61.8 | 59.6 | 60.4 | 0 |
| 10/20/2003 14:00:00 | 61.1 | 61.9 | 60.4 | 62.19 | 0 |
| 10/20/2003 15:00:00 | 61.8 | 62.4 | 61.3 | 61.34 | 0 |
| 10/20/2003 16:00:00 | 61.7 | 62.2 | 61 | 62.69 | 0 |
| 10/20/2003 17:00:00 | 59.9 | 61.7 | 57.1 | 68.05 | 0 |
| 10/20/2003 18:00:00 | 54.9 | 57.2 | 52.9 | 82.6 | 0 |
| 10/20/2003 19:00:00 | 52.1 | 53.2 | 50.9 | 91.6 | 0 |
| 10/20/2003 20:00:00 | 50.5 | 52.1 | 49.6 | 95 | 0 |
| 10/20/2003 21:00:00 | 50.1 | 53 | 48.6 | 97.3 | 0 |
| 10/20/2003 22:00:00 | 52.5 | 53.8 | 49.9 | 97 | 0 |
| 10/20/2003 23:00:00 | 54.1 | 55.8 | 52.8 | 95.9 | 0 |
| 10/21/2003 00:00:00 | 56.2 | 58.2 | 54.7 | 95.4 | 0 |
| 10/21/2003 01:00:00 | 58.4 | 59.6 | 57 | 93 | 0 |
| 10/21/2003 02:00:00 | 58.7 | 59.7 | 57.6 | 92.8 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/22/2003 15:00:00 | 53.4 | 54 | 52.9 | 67.26 | 0 |
| 10/22/2003 16:00:00 | 53.8 | 55.2 | 53 | 60.9 | 0 |
| 10/22/2003 17:00:00 | 52.7 | 53.6 | 51.7 | 55.96 | 0 |
| 10/22/2003 18:00:00 | 50.4 | 52.1 | 49 | 55.99 | 0 |
| 10/22/2003 19:00:00 | 47.8 | 49.1 | 47 | 62.61 | 0 |
| 10/22/2003 20:00:00 | 47 | 47.6 | 46.5 | 64.2 | 0 |
| 10/22/2003 21:00:00 | 46.4 | 47.1 | 45.6 | 63.04 | 0 |
| 10/22/2003 22:00:00 | 45.1 | 46.1 | 44.2 | 64.12 | 0 |
| 10/22/2003 23:00:00 | 44.4 | 44.9 | 43.7 | 57.34 | 0 |
| 10/23/2003 00:00:00 | 43.5 | 44.5 | 42.1 | 59.12 | 0 |
| 10/23/2003 01:00:00 | 42.3 | 42.9 | 41.8 | 66.12 | 0 |
| 10/23/2003 02:00:00 | 42 | 42.4 | 41.2 | 64.67 | 0 |
| 10/23/2003 03:00:00 | 41.1 | 42.2 | 39.9 | 60.97 | 0 |
| 10/23/2003 04:00:00 | 39.3 | 40.2 | 37.6 | 64.36 | 0 |
| 10/23/2003 05:00:00 | 37 | 38.1 | 36.2 | 74.28 | 0 |
| 10/23/2003 06:00:00 | 36.2 | 36.9 | 35.7 | 76.52 | 0 |
| 10/23/2003 07:00:00 | 36.2 | 37.8 | 35 | 78.67 | 0 |
| 10/23/2003 08:00:00 | 39.7 | 41.5 | 37.5 | 70.46 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/21/2003 21:00:00 | 67.9 | 68.8 | 67 | 54.01 | 0 |
| 10/21/2003 22:00:00 | 65.1 | 67.4 | 61.8 | 58.37 | 0 |
| 10/21/2003 23:00:00 | 61.3 | 62.1 | 60.4 | 70.99 | 0 |
| 10/22/2003 00:00:00 | 59.7 | 61 | 58.4 | 77.06 | 0 |
| 10/22/2003 01:00:00 | 58.9 | 59.8 | 58.2 | 78.13 | 0 |
| 10/22/2003 02:00:00 | 58.8 | 59.8 | 57.6 | 73.63 | 0 |
| 10/22/2003 03:00:00 | 57 | 58 | 56.1 | 78.07 | 0 |
| 10/22/2003 04:00:00 | 55.9 | 56.5 | 55.2 | 81.1 | 0 |
| 10/22/2003 05:00:00 | 54.8 | 56.3 | 52.9 | 82.6 | 0 |
| 10/22/2003 06:00:00 | 52.8 | 53.6 | 52.3 | 84.6 | 0 |
| 10/22/2003 07:00:00 | 52.1 | 52.6 | 51.4 | 81.9 | 0 |
| 10/22/2003 08:00:00 | 53.1 | 54.1 | 51.5 | 76.09 | 0 |
| 10/22/2003 09:00:00 | 54.7 | 55.9 | 53.8 | 73.2 | 0 |
| 10/22/2003 10:00:00 | 56.6 | 57.3 | 55.6 | 60.99 | 0 |
| 10/22/2003 11:00:00 | 58.2 | 60 | 56.6 | 54.83 | 0 |
| 10/22/2003 12:00:00 | 57.4 | 58.6 | 56.4 | 57.11 | 0 |
| 10/22/2003 13:00:00 | 57.4 | 59.6 | 56.4 | 57.89 | 0 |
| 10/22/2003 14:00:00 | 56.6 | 59.6 | 53 | 57.29 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/22/2003 15:00:00 | 53.4 | 54 | 52.9 | 67.26 | 0 |
| 10/22/2003 16:00:00 | 53.8 | 55.2 | 53 | 60.9 | 0 |
| 10/22/2003 17:00:00 | 52.7 | 53.6 | 51.7 | 55.96 | 0 |
| 10/22/2003 18:00:00 | 50.4 | 52.1 | 49 | 55.99 | 0 |
| 10/22/2003 19:00:00 | 47.8 | 49.1 | 47 | 62.61 | 0 |
| 10/22/2003 20:00:00 | 47 | 47.6 | 46.5 | 64.2 | 0 |
| 10/22/2003 21:00:00 | 46.4 | 47.1 | 45.6 | 63.04 | 0 |
| 10/22/2003 22:00:00 | 45.1 | 46.1 | 44.2 | 64.12 | 0 |
| 10/22/2003 23:00:00 | 44.4 | 44.9 | 43.7 | 57.34 | 0 |
| 10/23/2003 00:00:00 | 43.5 | 44.5 | 42.1 | 59.12 | 0 |
| 10/23/2003 01:00:00 | 42.3 | 42.9 | 41.8 | 66.12 | 0 |
| 10/23/2003 02:00:00 | 42 | 42.4 | 41.2 | 64.67 | 0 |
| 10/23/2003 03:00:00 | 41.1 | 42.2 | 39.9 | 60.97 | 0 |
| 10/23/2003 04:00:00 | 39.3 | 40.2 | 37.6 | 64.36 | 0 |
| 10/23/2003 05:00:00 | 37 | 38.1 | 36.2 | 74.28 | 0 |
| 10/23/2003 06:00:00 | 36.2 | 36.9 | 35.7 | 76.52 | 0 |
| 10/23/2003 07:00:00 | 36.2 | 37.8 | 35 | 78.67 | 0 |
| 10/23/2003 08:00:00 | 39.7 | 41.5 | 37.5 | 70.46 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/23/2003 09:00:00 | 42.9 | 44.8 | 41.2 | 60.1 | 0 |
| 10/23/2003 10:00:00 | 45.4 | 46.7 | 44.1 | 47.69 | 0 |
| 10/23/2003 11:00:00 | 44.8 | 45.5 | 44.1 | 43.87 | 0 |
| 10/23/2003 12:00:00 | 45.7 | 46.7 | 44.3 | 40.99 | 0 |
| 10/23/2003 13:00:00 | 45.4 | 46.1 | 44.9 | 43.86 | 0 |
| 10/23/2003 14:00:00 | 47.3 | 49.5 | 45 | 43.51 | 0 |
| 10/23/2003 15:00:00 | 47.3 | 48.9 | 46.1 | 43.71 | 0 |
| 10/23/2003 16:00:00 | 46.6 | 47.1 | 46.2 | 43.78 | 0 |
| 10/23/2003 17:00:00 | 46.9 | 47.7 | 46.1 | 44.3 | 0 |
| 10/23/2003 18:00:00 | 44 | 46.2 | 41.4 | 54.06 | 0 |
| 10/23/2003 19:00:00 | 39.1 | 41.7 | 37.4 | 73.81 | 0 |
| 10/23/2003 20:00:00 | 35.9 | 38.1 | 34.2 | 85.6 | 0 |
| 10/23/2003 21:00:00 | 35.6 | 37.4 | 33.9 | 87.9 | 0 |
| 10/23/2003 22:00:00 | 35.6 | 36.9 | 33.8 | 85 | 0 |
| 10/23/2003 23:00:00 | 34.7 | 37.2 | 33.1 | 86.5 | 0 |
| 10/24/2003 00:00:00 | 33 | 35.2 | 31.8 | 90.5 | 0 |
| 10/24/2003 01:00:00 | 31.7 | 33 | 30.8 | 94.7 | 0 |
| 10/24/2003 02:00:00 | 31.1 | 33 | 30.5 | 95 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/24/2003 03:00:00 | 30.6 | 31.4 | 29.9 | 96.5 | 0 |
| 10/24/2003 04:00:00 | 30.7 | 32.4 | 29.6 | 97 | 0 |
| 10/24/2003 05:00:00 | 33.2 | 34.2 | 32.1 | 92.2 | 0 |
| 10/24/2003 06:00:00 | 33.8 | 35 | 32.3 | 85.5 | 0 |
| 10/24/2003 07:00:00 | 34.6 | 35.5 | 33.9 | 80.1 | 0 |
| 10/24/2003 08:00:00 | 37.3 | 40.3 | 35.3 | 75.9 | 0 |
| 10/24/2003 09:00:00 | 43.4 | 46.5 | 39.9 | 65.98 | 0.01 |
| 10/24/2003 10:00:00 | 48.3 | 50.2 | 46.3 | 54.67 | 0 |
| 10/24/2003 11:00:00 | 51.5 | 52.6 | 49.7 | 48.88 | 0 |
| 10/24/2003 12:00:00 | 53.7 | 55.3 | 52 | 46.17 | 0 |
| 10/24/2003 13:00:00 | 54.6 | 55.9 | 53.5 | 43.21 | 0 |
| 10/24/2003 14:00:00 | 55.2 | 57.5 | 54 | 43.19 | 0 |
| 10/24/2003 15:00:00 | 56.2 | 57.6 | 54.4 | 42.75 | 0 |
| 10/24/2003 16:00:00 | 55.1 | 56.1 | 54.4 | 44.07 | 0 |
| 10/24/2003 17:00:00 | 54 | 55.1 | 51.9 | 48.64 | 0 |
| 10/24/2003 18:00:00 | 48.2 | 52.2 | 44.3 | 66.22 | 0 |
| 10/24/2003 19:00:00 | 43.4 | 44.8 | 42 | 81.5 | 0 |
| 10/24/2003 20:00:00 | 41 | 42.3 | 39.3 | 89.1 | 0 |

| Date and Time | Average Temp (°F) | Maximum Temp (°F) | Minimum Temp (°F) | Relative Humidity (%) | Total Precip (in) |
|---|---|---|---|---|---|
| 10/24/2003 21:00:00 | 39.3 | 41 | 38.1 | 92.7 | 0 |
| 10/24/2003 22:00:00 | 37.9 | 39 | 37.2 | 96.4 | 0 |
| 10/24/2003 23:00:00 | 37.3 | 38 | 36.7 | 97.9 | 0 |

# APPENDIX C.  SOIL MOISTURE

## Demonstrator:  G-TEK

Date:  14 October 2003
Times:  No AM Readings, 1600 hours

| Probe Location: | Layer, in. | AM Reading, % | PM Reading, % |
|---|---|---|---|
| Wet Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Wooded Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Open Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Calibration Lanes | 0 to 6 | No Readings Taken | 39.5 |
| | 6 to 12 | | 37.7 |
| | 12 to 24 | | 0.8 |
| | 24 to 36 | | 4.5 |
| | 36 to 48 | | 4.6 |
| Blind Grid/Moguls | 0 to 6 | No Readings Taken | 2.7 |
| | 6 to 12 | | 23.4 |
| | 12 to 24 | | 36.6 |
| | 24 to 36 | | 35.8 |
| | 36 to 48 | | 37.9 |

Date: 15 October 2003
Times: 0800 hours, 1600 hours

| Probe Location: | Layer, in. | AM Reading, % | PM Reading, % |
|---|---|---|---|
| Wet Area | 0 to 6 | 60.2 | 59.1 |
| | 6 to 12 | 73.1 | 73.6 |
| | 12 to 24 | 76.8 | 76.3 |
| | 24 to 36 | 53.7 | 54.0 |
| | 36 to 48 | 48.4 | 49.1 |
| Wooded Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Open Area | 0 to 6 | 22.1 | 20.2 |
| | 6 to 12 | 6.3 | 5.7 |
| | 12 to 24 | 16.8 | 17.3 |
| | 24 to 36 | 26.7 | 26.1 |
| | 36 to 48 | 49.9 | 51.3 |
| Calibration Lanes | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Blind Grid/Moguls | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |

Date: 16 October 2003
Times: 0830 hours, 1445 hours

| Probe Location: | Layer, in. | AM Reading, % | PM Reading, % |
|---|---|---|---|
| Wet Area | 0 to 6 | 69.4 | 70.1 |
| | 6 to 12 | 73.1 | 73.8 |
| | 12 to 24 | 71.9 | 70.9 |
| | 24 to 36 | 54.8 | 54.2 |
| | 36 to 48 | 50.1 | 49.7 |
| Wooded Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Open Area | 0 to 6 | 18.1 | 17.6 |
| | 6 to 12 | 0.3 | 0.3 |
| | 12 to 24 | 18.9 | 18.7 |
| | 24 to 36 | 21.9 | 21.6 |
| | 36 to 48 | 29.3 | 29.7 |
| Calibration Lanes | 0 to 6 | | |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | No Readings Taken | No Readings Taken |
| Blind Grid/Moguls | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |

Date: 17 October 2003
Times: 0825 hours, 1600 hours

| Probe Location: | Layer, in. | AM Reading, % | PM Reading, % |
|---|---|---|---|
| Wet Area | 0 to 6 | 70.2 | 70.8 |
| | 6 to 12 | 72.5 | 73.1 |
| | 12 to 24 | 72.2 | 71.8 |
| | 24 to 36 | 52.6 | 53.1 |
| | 36 to 48 | 49.1 | 48.8 |
| Wooded Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Open Area | 0 to 6 | 16.5 | 16.6 |
| | 6 to 12 | 0.2 | 0.4 |
| | 12 to 24 | 19.2 | 18.9 |
| | 24 to 36 | 22.3 | 21.9 |
| | 36 to 48 | 29.8 | 29.9 |
| Calibration Lanes | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Blind Grid/Moguls | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |

Date: 18 October 2003
Times: 0845 hours, 1400 hours

| Probe Location: | Layer, in. | AM Reading, % | PM Reading, % |
|---|---|---|---|
| Wet Area | 0 to 6 | 69.3 | 69.1 |
| | 6 to 12 | 71.3 | 72.8 |
| | 12 to 24 | 71.8 | 71.2 |
| | 24 to 36 | 52.5 | 53.5 |
| | 36 to 48 | 49.7 | 50.1 |
| Wooded Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Open Area | 0 to 6 | 15.7 | 15.6 |
| | 6 to 12 | 0.3 | 0.4 |
| | 12 to 24 | 18.3 | 18.9 |
| | 24 to 36 | 21.8 | 21.2 |
| | 36 to 48 | 29.3 | 29.1 |
| Calibration Lanes | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Blind Grid/Moguls | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |

Date: 20 October 2003
Times: 0800, 1600 hours

| Probe Location: | Layer, in. | AM Reading, % | PM Reading, % |
|---|---|---|---|
| Wet Area | 0 to 6 | 78.6 | 78.1 |
| | 6 to 12 | 75.3 | 75.0 |
| | 12 to 24 | 68.7 | 69.0 |
| | 24 to 36 | 51.8 | 52.1 |
| | 36 to 48 | 48.1 | 48.2 |
| Wooded Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Open Area | 0 to 6 | 12.4 | 12.2 |
| | 6 to 12 | 2.1 | 2.3 |
| | 12 to 24 | 14.6 | 14.4 |
| | 24 to 36 | 20.8 | 20.8 |
| | 36 to 48 | 25.6 | 25.3 |
| Calibration Lanes | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Blind Grid/Moguls | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |

Date:  21 October 2003
Times:  0800 hours, 1600 hours

| Probe Location: | Layer, in. | AM Reading, % | PM Reading, % |
|---|---|---|---|
| Wet Area | 0 to 6 | 77.8 | 77.6 |
| | 6 to 12 | 75.8 | 75.9 |
| | 12 to 24 | 69.3 | 69.2 |
| | 24 to 36 | 52.3 | 52.4 |
| | 36 to 48 | 49.3 | 49.7 |
| Wooded Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Open Area | 0 to 6 | 11.9 | 11.9 |
| | 6 to 12 | 2.2 | 2.4 |
| | 12 to 24 | 14.7 | 14.5 |
| | 24 to 36 | 21.2 | 21.3 |
| | 36 to 48 | 26.3 | 26.1 |
| Calibration Lanes | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Blind Grid/Moguls | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |

Date: 22 October 2003
Times: 0800 hours, 1600 hours

| Probe Location: | Layer, in. | AM Reading, % | PM Reading, % |
|---|---|---|---|
| Wet Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Wooded Area | 0 to 6 | 11.8 | 12.2 |
| | 6 to 12 | 5.7 | 5.1 |
| | 12 to 24 | 4.3 | 4.4 |
| | 24 to 36 | 51.8 | 51.4 |
| | 36 to 48 | 54.3 | 53.9 |
| Open Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Calibration Lanes | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Blind Grid/Moguls | 0 to 6 | 4.4 | 4.5 |
| | 6 to 12 | 9.6 | 9.3 |
| | 12 to 24 | 34.8 | 34.9 |
| | 24 to 36 | 36.7 | 36.2 |
| | 36 to 48 | 38.5 | 38.8 |

Date: 23 October 2003
Times: 0800 hours, 1400 hours

| Probe Location: | Layer, in. | AM Reading, % | PM Reading, % |
|---|---|---|---|
| Wet Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Wooded Area | 0 to 6 | 12.1 | 12.0 |
| | 6 to 12 | 6.2 | 5.9 |
| | 12 to 24 | 4.7 | 4.4 |
| | 24 to 36 | 52.3 | 52.0 |
| | 36 to 48 | 54.7 | 54.2 |
| Open Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Calibration Lanes | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Blind Grid/Moguls | 0 to 6 | 4.3 | 4.1 |
| | 6 to 12 | 9.5 | 9.4 |
| | 12 to 24 | 34.8 | 35.0 |
| | 24 to 36 | 36.3 | 36.2 |
| | 36 to 48 | 38.1 | 37.8 |

Date: 24 October 2003
Times: 0800 hours, 1600 hours

| Probe Location: | Layer, in. | AM Reading, % | PM Reading, % |
|---|---|---|---|
| Wet Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Wooded Area | 0 to 6 | 12.2 | 11.9 |
| | 6 to 12 | 6.7 | 6.4 |
| | 12 to 24 | 4.8 | 4.9 |
| | 24 to 36 | 52.7 | 52.4 |
| | 36 to 48 | 55.2 | 54.6 |
| Open Area | 0 to 6 | No Readings Taken | No Readings Taken |
| | 6 to 12 | | |
| | 12 to 24 | | |
| | 24 to 36 | | |
| | 36 to 48 | | |
| Calibration Lanes | 0 to 6 | No Readings Taken | 39.2 |
| | 6 to 12 | | 36.2 |
| | 12 to 24 | | 0.5 |
| | 24 to 36 | | 4.1 |
| | 36 to 48 | | 3.8 |
| Blind Grid/Moguls | 0 to 6 | 4.5 | 4.0 |
| | 6 to 12 | 9.7 | 9.7 |
| | 12 to 24 | 34.9 | 34.5 |
| | 24 to 36 | 36.7 | 36.2 |
| | 36 to 48 | 38.4 | 38.7 |

# APPENDIX D.   DAILY LOG OF ACTIVITIES

## TM-5 EMU DUAL SENSOR

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Status Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions |
|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/14/2003 | 2 | CALIBRATION LANE | 1015 | 1300 | 165 | INITIAL SET UP | INITIAL SET UP | GPS | NA | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 2 | CALIBRATION LANE | 1300 | 1310 | 10 | CALIBRATE | CALIBRATE EQUIPMENT USING METAL OBJECTS | GPS | NA | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 2 | CALIBRATION LANE | 1310 | 1430 | 80 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 2 | CALIBRATION LANE | 1430 | 1440 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | GPS | NA | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 2 | BLIND TEST GRID | 1440 | 1530 | 50 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 2 | BLIND TEST GRID | 1530 | 1540 | 10 | BREAK/LUNCH | BREAK/LUNCH | GPS | NA | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 2 | BLIND TEST GRID | 1540 | 1600 | 20 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 2 | BLIND TEST GRID | 1600 | 1630 | 30 | CALIBRATE | CALIBRATE EQUIPMENT USING METAL OBJECTS | GPS | NA | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 2 | BLIND TEST GRID | 1630 | 1745 | 75 | DOWNTIME MAINTENANCE CHECK | CHECKED GPS EQUIPMENT | GPS | NA | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 2 | BLIND TEST GRID | 1745 | 1815 | 30 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | GPS | NA | LINEAR | WINDY MUDDY |

## TM-5 EMU DUAL SENSOR

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/15/2003 | 2 | OPEN FIELD | 800 | 1015 | 135 | DAILY START/STOP | START OF DAILY OPERATIONS | GPS | NA | LINEAR | WINDY | MUDDY |
| 10/15/2003 | 2 | OPEN FIELD | 1015 | 1100 | 45 | DAILY START/STOP | SET UP SPACING WITH TAPES | GPS | NA | LINEAR | WINDY | MUDDY |
| 10/15/2003 | 2 | OPEN FIELD | 1100 | 1115 | 15 | CALIBRATE | CALIBRATE EQUIPMENT USING METAL OBJECTS | GPS | NA | LINEAR | WINDY | MUDDY |
| 10/15/2003 | 2 | OPEN FIELD | 1115 | 1245 | 90 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | WINDY | MUDDY |
| 10/15/2003 | | OPEN FIELD | | 1300 | 45 | DOWNTIME MAINTENANCE CHECK | EQUIPMENT CHECK, PUT TAPE ON SENSORS TO PREVENT WATER DAMAGE | | | | | |
| 10/15/2003 | 2 | OPEN FIELD | 1245 | 1400 | 60 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | WINDY | MUDDY |
| 10/15/2003 | 2 | OPEN FIELD | 1300 | 1405 | 5 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | WINDY | MUDDY |
| 10/15/2003 | 2 | OPEN FIELD | 1400 | 1710 | 185 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | WINDY | MUDDY |
| 10/15/2003 | 2 | OPEN FIELD | 1405 | 1800 | 50 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | GPS | NA | LINEAR | SUNNY | MUDDY |

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions |
|---|---|---|---|---|---|---|---|---|---|---|---|
| | | | | | | TM-5 EMU DUAL SENSOR | | | | | |
| 10/16/2003 | 2 | OPEN FIELD | 800 | 845 | 45 | DAILY START/STOP | START OF DAILY OPERATIONS | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/16/2003 | 2 | OPEN FIELD | 845 | 900 | 15 | CALIBRATE | CALIBRATE EQUIPMENT USING METAL OBJECTS | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/16/2003 | 2 | OPEN FIELD | 900 | 1010 | 70 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/16/2003 | 2 | OPEN FIELD | 1010 | 1020 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/16/2003 | 2 | OPEN FIELD | 1020 | 1310 | 170 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/16/2003 | 2 | OPEN FIELD | 1310 | 1315 | 5 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/16/2003 | 2 | OPEN FIELD | 1315 | 1700 | 225 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/16/2003 | 2 | OPEN FIELD | 1700 | 1730 | 30 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/17/2003 | 2 | OPEN FIELD | 730 | 850 | 80 | DAILY START/STOP | START OF DAILY OPERATIONS | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/17/2003 | 2 | OPEN FIELD | 850 | 910 | 20 | DAILY START/STOP | SET UP SPACING TAPES | GPS | NA | LINEAR | SUNNY MUDDY |

**TM-5 EMU DUAL SENSOR**

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions |
|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/17/2003 | 2 | OPEN FIELD | 910 | 930 | 20 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/17/2003 | 2 | OPEN FIELD | 930 | 955 | 25 | DAILY START/STOP | SET UP SPACING WITH TAPES | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/17/2003 | 2 | OPEN FIELD | 955 | 1100 | 65 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/17/2003 | 2 | OPEN FIELD | 1100 | 1110 | 10 | BREAK/LUNCH | BREAK/LUNCH | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/17/2003 | 2 | OPEN FIELD | 1110 | 1140 | 30 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/17/2003 | 2 | OPEN FIELD | 1140 | 1150 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/17/2003 | 2 | OPEN FIELD | 1150 | 1350 | 120 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/17/2003 | 2 | OPEN FIELD | 1350 | 1410 | 20 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/17/2003 | 2 | OPEN FIELD | 1410 | 1600 | 110 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY MUDDY |
| 10/17/2003 | 2 | OPEN FIELD | 1600 | 1640 | 40 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | GPS | NA | LINEAR | SUNNY MUDDY |

## TM-5 EMU DUAL SENSOR

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/18/2003 | 2 | OPEN FIELD | 725 | 810 | 45 | DAILY START/STOP | START OF DAILY OPERATIONS | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/18/2003 | 2 | OPEN FIELD | 810 | 840 | 30 | CALIBRATE | CALIBRATE EQUIPMENT USING METAL OBJECTS | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/18/2003 | 2 | OPEN FIELD | 840 | 1040 | 120 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/18/2003 | 2 | OPEN FIELD | 1040 | 1100 | 20 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/18/2003 | 2 | OPEN FIELD | 1100 | 1220 | 80 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/18/2003 | 2 | OPEN FIELD | 1220 | 1230 | 10 | BREAK/LUNCH | BREAK/LUNCH | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/18/2003 | 2 | OPEN FIELD | 1230 | 1325 | 55 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/18/2003 | 2 | OPEN FIELD | 1325 | 1335 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/18/2003 | 2 | OPEN FIELD | 1335 | 1605 | 150 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/18/2003 | 2 | OPEN FIELD | 1605 | 1640 | 35 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | GPS | NA | LINEAR | SUNNY | MUDDY |

**TM-5 EMU DUAL SENSOR**

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/20/2003 | 2 | OPEN FIELD | 745 | 830 | 45 | DAILY START/STOP | START OF DAILY OPERATIONS | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/20/2003 | 2 | OPEN FIELD | 830 | 850 | 20 | CALIBRATE | CALIBRATE EQUIPMENT USING METAL OBJECTS | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/20/2003 | 2 | OPEN FIELD | 850 | 1100 | 130 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/20/2003 | 2 | OPEN FIELD | 1100 | 1105 | 5 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/20/2003 | 2 | OPEN FIELD | 1105 | 1115 | 10 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/20/2003 | 2 | OPEN FIELD | 1115 | 1130 | 15 | DOWNTIME MAINTENANCE CHECK | DATA CHECK | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/20/2003 | 2 | OPEN FIELD | 1130 | 1300 | 90 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/20/2003 | 2 | OPEN FIELD | 1300 | 1350 | 50 | BREAK/LUNCH | BREAK/LUNCH | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/20/2003 | 2 | OPEN FIELD | 1350 | 1410 | 20 | DAILY START/STOP | SET UP SPACING WITH TAPES | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/20/2003 | 2 | OPEN FIELD | 1410 | 1450 | 40 | DOWNTIME MAINTENANCE CHECK | EQUIPMENT CHECK | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/20/2003 | 2 | OPEN FIELD | 1450 | 1555 | 65 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY | MUDDY |

**TM-5 EMU DUAL SENSOR**

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/20/2003 | 2 | OPEN FIELD | 1555 | 1610 | 15 | DOWNTIME MAINTENANCE CHECK | DATA CHECK | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/20/2003 | 2 | OPEN FIELD | 1610 | 1655 | 45 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/20/2003 | 2 | OPEN FIELD | 1655 | 1730 | 35 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 2 | OPEN FIELD | 735 | 910 | 95 | DAILY START/STOP | START OF DAILY OPERATIONS | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 2 | OPEN FIELD | 910 | 940 | 30 | CALIBRATE | CALIBRATE EQUIPMENT USING METAL OBJECTS | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 2 | OPEN FIELD | 940 | 1030 | 50 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 2 | OPEN FIELD | 1030 | 1105 | 35 | DOWNTIME MAINTENANCE CHECK | DATA CHECK | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 2 | OPEN FIELD | 1105 | 1315 | 130 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 2 | OPEN FIELD | 1315 | 1330 | 15 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 2 | OPEN FIELD | 1330 | 1450 | 80 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY | MUDDY |

## TM-5 EMU DUAL SENSOR

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/21/2003 | 2 | OPEN FIELD | 1450 | 1520 | 30 | DOWNTIME MAINTENANCE CHECK | DATA CHECK | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 2 | OPEN FIELD | 1520 | 1610 | 50 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 2 | OPEN FIELD | 1610 | 1630 | 20 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | GPS | NA | LINEAR | SUNNY | MUDDY |
| 10/22/2003 | 2 | MOGUL AREA | 735 | 945 | 130 | DAILY START/STOP | START OF DAILY OPERATIONS | GPS | NA | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 2 | MOGUL AREA | 945 | 1000 | 15 | CALIBRATE | CALIBRATE EQUIPMENT USING METAL OBJECTS | GPS | NA | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 2 | MOGUL AREA | 1000 | 1150 | 110 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 2 | MOGUL AREA | 1150 | 1200 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | GPS | NA | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 2 | MOGUL AREA | 1200 | 1315 | 75 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 2 | MOGUL AREA | 1315 | 1355 | 40 | DOWNTIME MAINTENANCE CHECK | DATA CHECK | GPS | NA | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 2 | MOGUL AREA | 1355 | 1705 | 190 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | CLOUDY | MUDDY |

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Status Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions |
|---|---|---|---|---|---|---|---|---|---|---|---|
| | | | | | | **TM-5 EMU DUAL SENSOR** | | | | | |
| 10/22/2003 | 2 | MOGUL AREA | 1705 | 1730 | 25 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | GPS | NA | LINEAR | CLOUDY MUDDY |
| 1023/2003 | 2 | WOODED AREA | 730 | 810 | 40 | DAILY START/STOP | START OF DAILY OPERATIONS | GPS | NA | LINEAR | CLOUDY MUDDY |
| 1023/2003 | 2 | WOODED AREA | 810 | 830 | 20 | CALIBRATE | CALIBRATE EQUIPMENT USING METAL OBJECTS | GPS | NA | LINEAR | CLOUDY MUDDY |
| 1023/2003 | 2 | WOODED AREA | 830 | 930 | 60 | COLLECT DATA | COLLECT DATA | GPS | NA | LINEAR | CLOUDY MUDDY |
| | | | | | | **TM-5 EMU SINGLE SENSOR** | | | | | |
| 1023/2003 | 2 | WOODED AREA | 930 | 1045 | 75 | COLLECT DATA | STARTED USING SINGLE HEAD AND COTTON MARKING SYSTEM | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| 1023/2003 | 2 | WOODED AREA | 1045 | 1105 | 20 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| 1023/2003 | 2 | WOODED AREA | 1105 | 1330 | 145 | COLLECT DATA | COLLECT DATA | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| 1023/2003 | 2 | WOODED AREA | 1330 | 1400 | 30 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY, DATA CHECK | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| 1023/2003 | 2 | WOODED AREA | 1400 | 1500 | 60 | COLLECT DATA | COLLECT DATA | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |

TM-5 EMU SINGLE SENSOR

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions |
|---|---|---|---|---|---|---|---|---|---|---|---|
| TM-5 EMU DUAL SENSOR | 2 | WOODED AREA | 1500 | 1615 | 75 | COLLECT DATA | COLLECT DATA | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| 1023/2003 | 2 | WOODED AREA | 1615 | 1630 | 15 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 2 | WOODED AREA | 800 | 815 | 15 | DAILY START/STOP | START OF DAILY OPERATIONS | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 2 | WOODED AREA | 815 | 830 | 15 | COLLECT DATA | COLLECT DATA | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 2 | WOODED AREA | 830 | 845 | 15 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 2 | WOODED AREA | 845 | 930 | 45 | COLLECT DATA | COLLECT DATA | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 2 | CALIBRATION LANE | 930 | 945 | 15 | CALIBRATE | CALIBRATE EQUIPMENT USING METAL OBJECTS | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 2 | CALIBRATION LANE | 945 | 1115 | 90 | COLLECT DATA | COLLECT DATA IN TEST PIT | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 2 | CALIBRATION LANE | 1115 | 1200 | 45 | DEMOBILIZATION | DEMOBILIZATION | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 2 | CALIBRATION LANE | 1200 | 1220 | 20 | COLLECT DATA | COLLECT DATA | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions |
|---|---|---|---|---|---|---|---|---|---|---|---|
| TM-5 EMU SINGLE SENSOR | | | | | | | | | | | |
| 10/24/2003 | 2 | BLIND TEST GRID | 1220 | 1245 | 25 | COLLECT DATA | COLLECT DATA | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 2 | BLIND TEST GRID | 1245 | 1505 | 140 | DEMOBILIZATION | DEMOBILIZATION | NA | COTTON ODOMETER | LINEAR | CLOUDY MUDDY |
| MAGNETOMETER | | | | | | | | | | | |
| 10/14/2003 | 3 | CALIBRATION LANE | 1015 | 1525 | 310 | INITIAL SET UP | INITIAL SET UP | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 3 | CALIBRATION LANE | 1525 | 1615 | 50 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 3 | CALIBRATION LANE | 1615 | 1620 | 5 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 3 | BLIND TEST GRID | 1620 | 1640 | 20 | DAILY START/STOP | SET UP SPACING TAPES | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 3 | BLIND TEST GRID | 1640 | 1720 | 40 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 3 | BLIND TEST GRID | 1720 | 1725 | 5 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 3 | BLIND TEST GRID | 1725 | 1745 | 20 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/14/2003 | 3 | BLIND TEST GRID | 1745 | 1815 | 30 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | NA | GPS | LINEAR | CLOUDY MUDDY |

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

**MAGNETOMETER**

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/15/2003 | 3 | OPEN FIELD | 800 | 1015 | 135 | DAILY START/STOP | START OF DAILY OPERATIONS | NA | GPS | LINEAR | WINDY | MUDDY |
| 10/15/2003 | 3 | OPEN FIELD | 1015 | 1145 | 90 | DAILY START/STOP | SET UP SPACING TAPES | NA | GPS | LINEAR | WINDY | MUDDY |
| 10/15/2003 | 3 | OPEN FIELD | 1145 | 1210 | 25 | CALIBRATE | CALIBRATE | NA | GPS | LINEAR | WINDY | MUDDY |
| 10/15/2003 | 3 | OPEN FIELD | 1210 | 1245 | 35 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | WINDY | MUDDY |
| 10/15/2003 | 3 | OPEN FIELD | 1245 | 1300 | 15 | DOWNTIME MAINTENANCE CHECK | EQUIPMENT CHECK, PUT TAPE ON SENSORS TO PREVENT WATER DAMAGE | NA | GPS | LINEAR | WINDY | |
| 10/15/2003 | 3 | OPEN FIELD | 1300 | 1500 | 120 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | WINDY | MUDDY |
| 10/15/2003 | 3 | OPEN FIELD | 1500 | 1515 | 15 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | WINDY | MUDDY |
| 10/15/2003 | 3 | OPEN FIELD | 1515 | 1600 | 45 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | WINDY | MUDDY |
| 10/15/2003 | 3 | OPEN FIELD | 1600 | 1615 | 15 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | WINDY | MUDDY |
| 10/15/2003 | 3 | OPEN FIELD | 1615 | 1715 | 60 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | WINDY | MUDDY |

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

**MAGNETOMETER**

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/15/2003 | 3 | OPEN FIELD | 1715 | 1800 | 45 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | NA | GPS | LINEAR | WINDY | MUDDY |
| 10/16/2003 | 3 | OPEN FIELD | 800 | 845 | 45 | DAILY START/STOP | START OF DAILY OPERATIONS | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/16/2003 | 3 | OPEN FIELD | 845 | 930 | 45 | CALIBRATE | CALIBRATE | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/16/2003 | 3 | OPEN FIELD | 930 | 1050 | 80 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/16/2003 | 3 | OPEN FIELD | 1050 | 1100 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/16/2003 | 3 | OPEN FIELD | 1100 | 1210 | 70 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/16/2003 | 3 | OPEN FIELD | 1210 | 1215 | 5 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/16/2003 | 3 | OPEN FIELD | 1215 | 1345 | 90 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/16/2003 | 3 | OPEN FIELD | 1345 | 1510 | 85 | DAILY START/STOP | SET UP SPACING TAPES | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/16/2003 | 3 | OPEN FIELD | 1510 | 1640 | 90 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/16/2003 | 3 | OPEN FIELD | 1640 | 1645 | 45 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY | MUDDY |

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

## MAGNETOMETER

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Status Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/16/2003 | 3 | OPEN FIELD | 1645 | 1700 | 15 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/16/2003 | 3 | OPEN FIELD | 1700 | 1730 | 30 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/17/2003 | 3 | OPEN FIELD | 730 | 910 | 100 | DAILY START/STOP | START OF DAILY OPERATIONS | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/17/2003 | 3 | OPEN FIELD | 910 | 930 | 20 | CALIBRATE | CALIBRATE | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/17/2003 | 3 | OPEN FIELD | 930 | 1100 | 90 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/17/2003 | 3 | OPEN FIELD | 1100 | 1120 | 20 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/17/2003 | 3 | OPEN FIELD | 1120 | 1150 | 30 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/17/2003 | 3 | OPEN FIELD | 1150 | 1230 | 40 | DAILY START/STOP | SET UP SPACING TAPES | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/17/2003 | 3 | OPEN FIELD | 1230 | 1325 | 55 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/17/2003 | 3 | OPEN FIELD | 1325 | 1350 | 25 | EQUIPMENT FAILURE | BAD CABLE CONNECTION, RECONNECTED CABLES | NA | GPS | LINEAR | SUNNY | MUDDY |

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

## MAGNETOMETER

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions |
|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/17/2003 | 3 | OPEN FIELD | 1350 | 1445 | 55 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/17/2003 | 3 | OPEN FIELD | 1445 | 1500 | 15 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/17/2003 | 3 | OPEN FIELD | 1500 | 1550 | 50 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/17/2003 | 3 | OPEN FIELD | 1550 | 1640 | 50 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | | | | |
| 10/18/2003 | 3 | OPEN FIELD | 725 | 810 | 45 | DAILY START/STOP | START OF DAILY OPERATIONS | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 810 | 835 | 25 | CALIBRATE | CALIBRATE | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 835 | 940 | 65 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 940 | 950 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 950 | 1110 | 80 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 1110 | 1115 | 5 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 1115 | 1125 | 10 | EQUIPMENT FAILURE | BAD SATELLITE QUALITY | NA | GPS | LINEAR | SUNNY MUDDY |

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

**MAGNETOMETER**

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions |
|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/18/2003 | 3 | OPEN FIELD | 1125 | 1155 | 30 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 1155 | 1230 | 35 | BREAK/LUNCH | BREAK/LUNCH | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 1230 | 1300 | 30 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 1300 | 1325 | 25 | DAILY START/STOP | SET UP SPACING TAPES | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 1325 | 1420 | 55 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 1420 | 1425 | 5 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 1425 | 1520 | 55 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 1520 | 1535 | 15 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 1535 | 1610 | 35 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/18/2003 | 3 | OPEN FIELD | 1610 | 1640 | 30 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 745 | 845 | 60 | DAILY START/STOP | START OF DAILY OPERATIONS | NA | GPS | LINEAR | SUNNY MUDDY |

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

## MAGNETOMETER

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Status Duration, min | Operational Status | Operational Status – Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions |
|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/20/2003 | 3 | OPEN FIELD | 845 | 915 | 30 | CALIBRATE | CALIBRATE | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 915 | 1020 | 65 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 1020 | 1030 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 1030 | 1115 | 45 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 1115 | 1200 | 45 | DAILY START/STOP | SET UP SPACING TAPES | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 1200 | 1210 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 1210 | 1230 | 20 | BREAK/LUNCH | BREAK/LUNCH | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 1230 | 1320 | 50 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 1320 | 1330 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 1330 | 1500 | 90 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 1500 | 1505 | 5 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY MUDDY |

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

MAGNETOMETER

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions |
|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/20/2003 | 3 | OPEN FIELD | 1505 | 1525 | 20 | DAILY START/STOP | SET UP SPACING TAPES | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 1525 | 1615 | 50 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 1615 | 1625 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 1625 | 1700 | 35 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/20/2003 | 3 | OPEN FIELD | 1700 | 1730 | 30 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/21/2003 | 3 | OPEN FIELD | 735 | 820 | 45 | DAILY START/STOP | START OF DAILY OPERATIONS | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/21/2003 | 3 | OPEN FIELD | 820 | 900 | 40 | CALIBRATE | CALIBRATE | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/21/2003 | 3 | OPEN FIELD | 900 | 1010 | 70 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/21/2003 | 3 | OPEN FIELD | 1010 | 1030 | 20 | DOWNTIME MAINTENANCE CHECK | DOWNLOAD DATA | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/21/2003 | 3 | OPEN FIELD | 1030 | 1040 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY MUDDY |
| 10/21/2003 | 3 | OPEN FIELD | 1040 | 1100 | 20 | BREAK/LUNCH | BREAK/LUNCH | NA | GPS | LINEAR | SUNNY MUDDY |

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

## MAGNETOMETER

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/21/2003 | 3 | OPEN FIELD | 1100 | 1150 | 50 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 3 | OPEN FIELD | 1150 | 1200 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 3 | OPEN FIELD | 1200 | 1330 | 90 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 3 | OPEN FIELD | 1330 | 1345 | 15 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 3 | OPEN FIELD | 1345 | 1435 | 50 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 3 | OPEN FIELD | 1435 | 1445 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 3 | OPEN FIELD | 1445 | 1600 | 75 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/21/2003 | 3 | OPEN FIELD | 1600 | 1630 | 30 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | NA | GPS | LINEAR | SUNNY | MUDDY |
| 10/22/2003 | 3 | WOODED AREA | 735 | 935 | 120 | DAILY START/STOP | START OF DAILY OPERATIONS | NA | COTTON ODOMETER | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 3 | WOODED AREA | 935 | 1000 | 25 | CALIBRATE | CALIBRATE | NA | COTTON ODOMETER | LINEAR | CLOUDY | MUDDY |

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

**MAGNETOMETER**

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Duration, min | Operational Status | Operational Status – Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/22/2003 | 3 | WOODED AREA | 1000 | 1145 | 105 | COLLECT DATA | COLLECT DATA | NA | COTTON ODOMETER | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 3 | WOODED AREA | 1145 | 1205 | 20 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | COTTON ODOMETER | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 3 | WOODED AREA | 1205 | 1300 | 55 | COLLECT DATA | COLLECT DATA | NA | COTTON ODOMETER | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 3 | WOODED AREA | 1300 | 1305 | 5 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | COTTON ODOMETER | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 3 | WOODED AREA | 1305 | 1400 | 55 | COLLECT DATA | COLLECT DATA | NA | COTTON ODOMETER | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 3 | WOODED AREA | 1400 | 1410 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | COTTON ODOMETER | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 3 | WOODED AREA | 1410 | 1515 | 65 | COLLECT DATA | COLLECT DATA | NA | COTTON ODOMETER | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 3 | WOODED AREA | 1515 | 1520 | 5 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | COTTON ODOMETER | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 3 | WOODED AREA | 1520 | 1615 | 55 | COLLECT DATA | COLLECT DATA | NA | COTTON ODOMETER | LINEAR | CLOUDY | MUDDY |
| 10/22/2003 | 3 | WOODED AREA | 1615 | 1730 | 75 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | NA | COTTON ODOMETER | LINEAR | CLOUDY | MUDDY |

## MAGNETOMETER

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Status Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions | |
|---|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/23/2003 | 3 | MOGUL AREA | 730 | 900 | 90 | DAILY START/STOP | START OF DAILY OPERATIONS | NA | GPS | LINEAR | CLOUDY | MUDDY |
| 10/23/2003 | 3 | MOGUL AREA | 900 | 915 | 15 | CALIBRATE | CALIBRATE | NA | GPS | LINEAR | CLOUDY | MUDDY |
| 10/23/2003 | 3 | MOGUL AREA | 915 | 1015 | 60 | DAILY START/STOP | SET UP SPACING TAPES | NA | GPS | LINEAR | CLOUDY | MUDDY |
| 10/23/2003 | 3 | MOGUL AREA | 1015 | 1110 | 55 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | CLOUDY | MUDDY |
| 10/23/2003 | 3 | MOGUL AREA | 1110 | 1115 | 5 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | CLOUDY | MUDDY |
| 10/23/2003 | 3 | MOGUL AREA | 1115 | 1215 | 60 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | CLOUDY | MUDDY |
| 10/23/2003 | 3 | MOGUL AREA | 1215 | 1220 | 5 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | CLOUDY | MUDDY |
| 10/23/2003 | 3 | MOGUL AREA | 1220 | 1230 | 10 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | CLOUDY | MUDDY |
| 10/23/2003 | 3 | MOGUL AREA | 1230 | 1315 | 45 | DAILY START/STOP | SET UP SPACING TAPES | NA | GPS | LINEAR | CLOUDY | MUDDY |
| 10/23/2003 | 3 | MOGUL AREA | 1315 | 1410 | 55 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | CLOUDY | MUDDY |
| 10/23/2003 | 3 | MOGUL AREA | 1410 | 1420 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | CLOUDY | MUDDY |

**MAGNETOMETER**

| Date | No. of People | Area Tested | Status Start Time | Status Stop Time | Status Duration, min | Operational Status | Operational Status - Comments | Track Method | Track Method = Other Explain | Pattern | Field Conditions |
|---|---|---|---|---|---|---|---|---|---|---|---|
| 10/23/2003 | 3 | MOGUL AREA | 1420 | 1525 | 65 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/23/2003 | 3 | MOGUL AREA | 1525 | 1630 | 65 | DAILY START/STOP | EQUIPMENT BREAKDOWN/ END OF DAILY OPERATIONS | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 3 | CALIBRATION TEST PIT | 800 | 900 | 60 | DAILY START/STOP | START OF DAILY OPERATIONS | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 3 | CALIBRATION TEST PIT | 900 | 915 | 15 | CALIBRATE | CALIBRATE | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 3 | CALIBRATION TEST PIT | 915 | 1100 | 105 | COLLECT DATA | COLLECT DATA IN TEST PIT | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 3 | CALIBRATION TEST PIT | 1100 | 1110 | 10 | DOWNTIME MAINTENANCE CHECK | CHANGE BATTERY | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 3 | CALIBRATION TEST PIT | 1110 | 1125 | 15 | COLLECT DATA | COLLECT DATA IN TEST PIT | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 3 | CALIBRATION TEST PIT | 1125 | 1230 | 65 | BREAK/LUNCH | BREAK/LUNCH | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 3 | MOGUL AREA | 1230 | 1330 | 60 | COLLECT DATA | COLLECT DATA | NA | GPS | LINEAR | CLOUDY MUDDY |
| 10/24/2003 | 3 | MOGUL AREA | 1330 | 1505 | 95 | DEMOBILIZATION | DEMOBILIZATION | NA | GPS | LINEAR | CLOUDY MUDDY |

Note: Activities pertinent to this specific demonstration are indicated in highlighted text.

# APPENDIX E.   REFERENCES

1.  Standardized UXO Technology Demonstration Site Handbook, DTC Project No. 8-CO-160-000-473, Report No. ATC-8349, March 2002.

2.  Aberdeen Proving Ground Soil Survey Report, October 1998.

3.  Data Summary, UXO Standardized Test Site:  APG Soils Description, May 2002.

4.  Yuma Proving Ground Soil Survey Report, May 2003.

# APPENDIX F.   ABBREVIATIONS

| | | |
|---|---|---|
| AEC | = | U.S. Army Environmental Center |
| APG | = | Aberdeen Proving Ground |
| ASCII | = | American Standard Code for Information Interchange. |
| ATC | = | U.S. Army Aberdeen Test Center |
| DGPS | = | Digital Global Positioning |
| EM | = | electromagnetic |
| EMI | = | electromagnetic interference |
| EMIS | = | Electromagnetic Induction Spectroscopy |
| ERDC | = | U.S. Army Corps of Engineers Engineering Research and Development Center |
| ESTCP | = | Environmental Security Technology Certification Program |
| EQT | = | Army Environmental Quality Technology Program |
| GPS | = | Global Positioning System |
| JPG | = | Jefferson Proving Ground |
| NMEA | = | National Maritime Electronics Association |
| PC | = | Personal Computer |
| POC | = | point of contact |
| QA | = | quality assurance |
| QC | = | quality control |
| ROC | = | receiver-operating characteristic |
| RTK | = | real time kinematic |
| RTS | = | Robotic Total Station |
| SERDP | = | Strategic Environmental Research and Development Program |
| UXO | = | unexploded ordnance |
| YPG | = | U.S. Army Yuma Proving Ground |

# APPENDIX G.   DISTRIBUTION LIST

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